

## Appendix F

### Application: Static GPS Control Survey--Coyote Dam, Russian River, CA (Sacramento District)

This appendix provides an example of a static GPS surveys performed on a Corps civil works project performed during 1989. This survey was performed prior to full operational capability of the GPS satellite constellation; thus, observation windows had to be observed in order to obtain four or more satellites. The procedures and standards that were used for performing, reducing, and adjusting these early GPS surveys have not significantly changed, other than the more user-friendly field data collection devices and significantly updated Windows-based baseline reduction and adjustment software. Baseline reduction and adjustment software techniques shown on these 1989 surveys are still representative of the current reductions and analyses performed today--only the output formats have changes.

#### F-1. Planning Phase

The GPS survey was planned for 25 April 1989 in the vicinity of Coyote Dam on the East Fork of the Russian River, near Ukiah, California.

*a.* A diagram of the project area is shown in Figure F-1. Three fixed control points were connected--Calpella 1949, Perry 1949, and Ukiah Airport 1949.

*b.* Four Trimble 4000 SL GPS carrier phase tracking receivers were used for the survey--with one person per receiver. In actuality, because the personnel were inexperienced in conducting a GPS survey, a fifth person was also used. The fifth person was used as a "runner" who can be called upon during the survey to aid in smoothing out any complications (e.g., aiding in overall communication and coordination, parts retrieval in case of breakdown, bad power source, blown fuse, misplaced equipment, forgotten measurement device or power cord, as well as any other possible complication). Communication between personnel was by two-way radio. Care was taken in choosing and operating the two-way radio near the GPS survey so that the radio transmitter and receiver chosen, when in operation, would not interfere with the GPS receiver.

*c.* Prior to data collection, the stations were inspected and found to be acceptable (easy accessibility, no obstruction or possible multipath sources, and at least 20 degree satellite visibility above the horizon).

*d.* April 25, 1989 corresponds to Julian calendar day 115. Calpella, Perry, and Ukiah Airport were stations with established horizontal control. Pier 1 and Pier 2 were stations requiring horizontal coordinates accurate to 1:10,000 (refer to Figure F-2). Therefore, the following station conventions for Session 1 of the survey were:

Pier 1 - Station 20011151  
Pier 2 - Station 20021151  
Calpella - Station 20131151  
Ukiah Airport - Station 20141151

It is important to note that this station convention was used for this survey because the Trimble receiver only allowed numeric input of station names. Newer receivers allow alphanumeric inputs for station names, which provides more flexibility in station naming.

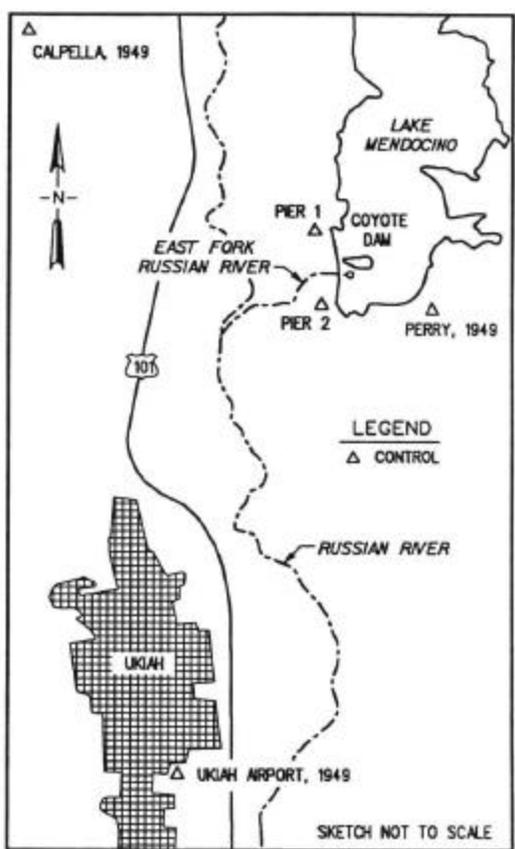


Figure F-1. Ukiah Project Area

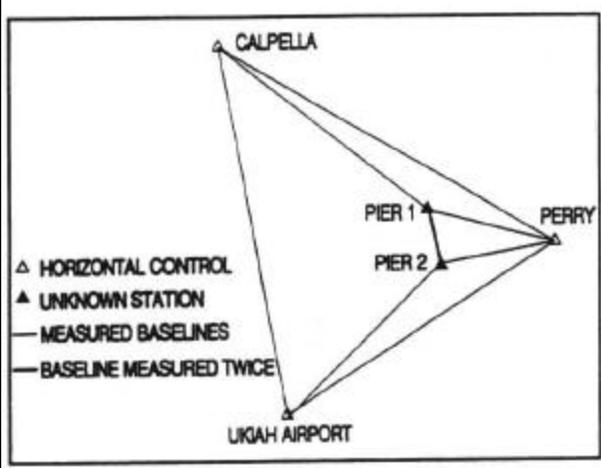


Figure F-2. GPS Project Diagram (Ukiah)

e. A satellite visibility plan (a software package that produces a hard copy listing of satellite constellations and time availability based on ephemerides) was run for the project location. The satellite visibility was run with the most up-to-date ephemeris for the period of observation, using four-satellite visibility, and with a cut-off elevation angle of 20 deg. An up-to-date ephemeris was used to ensure the satellite visibility formulated was the most accurate. A minimum of 4 visible satellites was specified in order to formulate accurate three-dimensional solutions. A cut-off elevation of 20 deg was chosen in order to minimize any diffusion or dispersion of the signal by the atmosphere which in turn may cause errors in the solution as the satellites pass near the horizon. The satellite visibility plan produced for the Ukiah project is shown below.

**All-In-View PDOP for UKIAH**

Date : 25 Feb 1990		Time : 4:00 -> 4:00			
Latitude : 39° 12' 30" N		Longitude : 123° 10' 30" W			
Cut-off Elevation : 20		Zone : - 7:00			
Satellite Constellation	Time Rise	Time Set	dT	PDOP Rise	PDOP Set
6 9 11 13	21:55	22:03	0:08	4.9	5.0
6 9 11 12 13	22:02	22:33	0:30	3.8	3.6
6 9 11 12 13 19	22:32	23:18	0:45	3.2	3.3
3 6 9 11 12 13 19	23:17	23:48	0:30	2.9	3.0
3 9 11 12 13 19	23:47	1:08	1:20	4.2	4.2
3 11 12 13 19	1:07	1:22	0:15	4.9	5.0
3 12 13 19	1:22	2:20	0:58	22.7	31.6

The portion of the satellite visibility where the PDOP is near 5.0 m/m or below are times when the satellite geometry is conducive for conduct of a survey. A PDOP near or below 5.0 m/m does not guarantee a successful survey but it does indicate good satellite geometry during that moment of the survey--see Chapter 5 for further information on PDOP.

f. From the satellite visibility plan, it was decided to conduct three sessions during the survey. Travel between survey sites, time to set up and take down the equipment before and after the survey, receiver warm up time, time of survey (at least an hour allotment for survey data collection, but more than an hour if at all possible), and possible time loss due to unforeseeable problems or complications were taken into account before deciding on a specific session schedule. The final survey session schedule is shown in the chart below:

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**Final Survey Session Schedule**

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Session	Start Time	Stop Time
1	21:55	22:55
2	23:38	00:38
3	01:23	02:20

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It was further decided which stations would be occupied during each session. Station occupation was designed to minimize travel time and to add to the overall efficiency of the survey. The station occupation schedule was planned as shown in the following chart:

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**Station Occupation Schedule**

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Session	Station	Station	Station	Station
1	Calpella	Ukiah Airport	Pier 1	Pier 2
2	Calpella	Perry	Pier 1	Pier 2
3	Ukiah Airport	Perry	Pier 1	Pier 2

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g. A GPS Station Observation Log is generally filled out prior to conduct of the survey. An example of a GPS Station Observation Log is shown in Figure F-3. The GPS Station Observation Log must be filled out for each of the station occupied in order to have a written record of the actual survey and as an aid for the personnel occupying each of the station.

h. Portions of the GPS Station Observation Log were filled out prior to data collection. These portions included the station name, start date, GPS 8 character ID for each session, project name, project location, observer name, approximate receiver position (latitude, longitude, and elevation), session scheduled start and stop times, and requisite tracking equipment information. In this case, six GPS Station Observation Logs were filled out, one each for: Calpella (Sessions 1 & 2), Ukiah Airport (Session 3), Ukiah Airport (Session 1), Perry (Sessions 1 & 2), Pier 1 (Sessions 1, 2, and 3), and Pier 2 (Sessions 1, 2, and 3). An example of a GPS Station Observation Log for Station "Pier 2" is shown in Figure F-4.

U.S. ARMY CORPS OF ENGINEERS GPS DATA LOGGING SHEET						
*****						
PROJECT NAME	_____		LOCALITY	_____		
OBSERVER	_____		AGENCY/FIRM	_____		
RECEIVER	_____		S/N	_____		
ANTENNA	_____		S/N	_____		
DATA RECORDING UNIT	_____		S/N	_____		
TRIBRACH	_____		S/N	LAST CALIBRATED: _____		
*****						
	SESSION 1		SESSION 2		SESSION 3	
STATION: NAME	_____		_____		_____	
NUMBER	_____		_____		_____	
DAY OF YEAR	_____		_____		_____	
DATE MM DD YY	_____		_____		_____	
UTC TIME OF OBSERVATION	START	STOP	START	STOP	START	STOP
	_____	_____	_____	_____	_____	_____
*****						
ANTENNA HEIGHT MEASUREMENTS						
	SESSION 1		SESSION 2		SESSION 3	
SLOPE @ BEGINNING	_____	IN= _____ M MN = _____ M	_____	IN= _____ M MN = _____ M	_____	IN= _____ M MN = _____ M
SLOPE @ END	_____	IN= _____ M MN = _____ M	_____	IN= _____ M MN = _____ M	_____	IN= _____ M MN = _____ M
MN ADJ TO VERT:	_____ M		_____ M		_____ M	
*****						
	PROGRAMMED	FIELD	PROGRAMMED	FIELD	PROGRAMMED	FIELD
	REFPOS	POSITION	REFPOS	POSITION	REFPOS	POSITION
LAT	_____	_____	_____	_____	_____	_____
LONG	_____	_____	_____	_____	_____	_____
HT	_____	_____	_____	_____	_____	_____
PDOP	_____	_____	_____	_____	_____	_____
SVS TO TRACK LOCAL	_____		_____		_____	
TIME: SCHEDULED	ACTUAL	SCHEDULED	ACTUAL	SCHEDULED	ACTUAL	
START	_____	_____	_____	_____	_____	
STOP	_____	_____	_____	_____	_____	
*****						
PAGE 1						
a. Front						

Figure F-3 a. Example GPS Station Observation Log (Front)

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GPS DATA LOGGING SHEET

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	SESSION 1	SESSION 2	SESSION 3
ANT CABLE LENGTH	_____	_____	_____
POWER SUPPLY	_____	_____	_____
WEATHER CONDITIONS	_____ _____	_____ _____	_____ _____
MONUMENT TYPE	_____	_____	_____
EXACT STAMPING	_____	_____	_____
AGENCY CAST IN DISK	_____	_____	_____

\*\*\*\*\*

SESSION 1	SKETCH OF SITE SESSSION 2	SESSION 3
<div style="border-bottom: 1px solid black; border-right: 1px dashed black; border-left: 1px dashed black; border-top: 1px solid black;"></div>	<div style="border-bottom: 1px solid black; border-right: 1px dashed black; border-left: 1px dashed black; border-top: 1px solid black;"></div>	<div style="border-bottom: 1px solid black; border-right: 1px dashed black; border-left: 1px dashed black; border-top: 1px solid black;"></div>

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Describe any abnormalities and/or problems encountered during the survey, include session number, time of occurence and duration.

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PAGE 2

b. Back

Figure F-3 b. Example GPS Station Observation Log (Back)

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GPS DATA LOGGING SHEET

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PROJECT NAME COYOTE DAM LOCALITY UKIAH, CA  
 OBSERVER LARRY LAMB AGENCY/FIRM COE, SACRAMENTO DISTRICT  
 RECEIVER TRIMBLE 4000 SL S/N 2820A00223  
 ANTENNA TRIMBLE MICRO SL S/N 2816A00224  
 DATA RECORDING UNIT RECEIVER S/N 2820A00224  
 TRIBRACH WILD GDF 22 S/N N/A LAST CALIBRATED: 4/24/89

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	SESSION 1	SESSION 2	SESSION 3
STATION: NAME	<u>PIER 2</u>	<u>PIER 2</u>	<u>PIER 2</u>
NUMBER	<u>2002</u>	<u>2002</u>	<u>2002</u>
DAY OF YEAR	<u>115</u>	<u>115</u>	<u>115</u>
DATE MM DD YY	<u>4/25/89</u>	<u>4/25/89</u>	<u>4/25/89</u>
UTC TIME OF OBSERVATION	START <u>04:56</u> STOP <u>05:55</u>	START <u>06:10</u> STOP <u>07:38</u>	START <u>07:55</u> STOP <u>09:20</u>

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ANTENNA HEIGHT MEASUREMENTS

	SESSION 1	SESSION 2	SESSION 3
SLOPE @ BEGINNING	IN= _____ M MN = _____ M	IN= _____ M MN = _____ M	IN= _____ M MN = _____ M
SLOPE @ END	IN= _____ M MN = _____ M	IN= _____ M MN = _____ M	IN= _____ M MN = _____ M
MN ADJ TO VERT:	_____ M	_____ M	_____ M

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	PROGRAMMED REFPOS	FIELD POSITION	PROGRAMMED REFPOS	FIELD POSITION	PROGRAMMED REFPOS	FIELD POSITION
LAT	<u>39-12-30</u>	_____	<u>39-12-30</u>	_____	<u>39-12-30</u>	_____
LONG	<u>123-10-30</u>	_____	<u>123-10-30</u>	_____	<u>123-10-30</u>	_____
HT	<u>244.0</u>	_____	<u>244.0</u>	_____	<u>244.0</u>	_____
PDOP	<u>3.6</u>	_____	<u>4.8</u>	_____	<u>4.0</u>	_____
SVS TO TRACK LOCAL	<u>02,03,06,09</u> <u>11,12,13,14</u>	_____	<u>02,03,06,09</u> <u>11,12,13,14</u>	_____	<u>03,06,09,11</u> <u>12,13,14,16</u>	_____
TIME: SCHEDULED	_____	_____	_____	_____	_____	_____
START	<u>21:55</u>	_____	<u>23:38</u>	_____	<u>01:20</u>	_____
STOP	<u>22:55</u>	_____	<u>00:38</u>	_____	<u>02:20</u>	_____

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PAGE 1

a. Front

Figure F-4. GPS Station Observation Log (Pre-Survey)

## F-2. Actual Survey Operation

Those portions of the GPS Station Observation Log, which were not filled out during the planning phase of the survey, were filled out during data collection. An example of the GPS Station Observation Log for Station "Pier 2", filled out after data collection, is shown in Figure F-5.

a. Key to proper data collection is correct set up of the equipment (tripod, receiver, and power source) and correct antenna height measurements (height of the antenna above the mark).

b. Figure F-6 shows personnel correctly taking an antenna height measurement over a temporary monument. Figure F-7 illustrates a typical antenna setup with the following equation detailing the antenna height correction.

$$v = \text{sqrt} [ s^2 - r^2 ]$$

where

$v$  = corrected vertical height distance of the antenna center above the mark,

$s$  = slope distance measurement derived from the average of several antenna height measurements

$r$  = antenna radius

c. When measuring the antenna height during this survey, the following procedure was followed in order to ensure an accurate reading:

(1) The slope distance from the North point of the antenna to the center of the monument was measured to the nearest millimeter (0.001 m). Measurement was also done in English units (inches) to the nearest 1/32<sup>th</sup> of an inch. This value then was compared to the metric value measured earlier. This comparison is done to detect blunders.

(2) Similar measurements are also taken from the South point of the antenna to the center of the monument.

(3) The resultant North and South slope distances were averaged.

(4) Example: (Refer to Figure F-5)

- Tripod set up flat on a dock.
- The North side measure up for session 1 = .120m
- The South side measure up for session 1 = .120m
- An extra "Check Measurement" was also taken for the measure up for Session 1 and was found to = 0.394 ft.
- As a check: (0.394 ft.) x (1m / 3.281 ft.) = .120m
- This value was recorded in the GPS Station Observation Log.

d. Each GPS receiver was operated in direct accordance with the manufacturer instructions, procedures, and/or guidance.

e. No problems were encountered during the survey sessions.

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PROJECT NAME COYOTE DAM LOCALITY UKIAH, CA  
 OBSERVER LARRY LAMB AGENCY/FIRM COE SACRAMENTO DISTRICT  
 RECEIVER TRIMBLE 4005L S/N 2820A00223  
 ANTENNA TRIMBLE 5800 SL S/N 2816A00224  
 DATA RECORDING UNIT RECEIVER S/N 2820A00224  
 TRIBRACH WILD GDF 22 S/N N/A LAST CALIBRATED: 4/24/89

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	SESSION 1	SESSION 2	SESSION 3
STATION: NAME	<u>PIER 2</u>	<u>PIER 2</u>	<u>PIER 2</u>
NUMBER	<u>2002</u>	<u>2002</u>	<u>2002</u>
DAY OF YEAR	<u>115</u>	<u>115</u>	<u>115</u>
DATE MM DD YY	<u>4/25/89</u>	<u>4/25/89</u>	<u>4/25/89</u>
UTC TIME OF OBSERVATION	START <u>04:56</u> STOP <u>05:55</u>	START <u>06:10</u> STOP <u>07:38</u>	START <u>07:55</u> STOP <u>09:20</u>

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ANTENNA HEIGHT MEASUREMENTS

	SESSION 1	SESSION 2	SESSION 3
SLOPE @ BEGINNING	<u>0.120</u> <u>0.120</u> <u>0.120</u> <u>4<sup>13</sup>/<sub>16</sub></u> IN = <u>0.121</u> M MN = <u>0.120</u> M	<u>0.116</u> <u>0.116</u> <u>0.116</u> <u>4<sup>9</sup>/<sub>16</sub></u> IN = <u>0.116</u> M MN = <u>0.116</u> M	<u>0.123</u> <u>0.124</u> <u>0.124</u> <u>4<sup>13</sup>/<sub>16</sub></u> IN = <u>0.124</u> M MN = <u>0.1238</u> M
SLOPE @ END	<u>4<sup>8</sup>/<sub>16</sub></u> <u>4<sup>12</sup>/<sub>16</sub></u> <u>4<sup>14</sup>/<sub>16</sub></u> <u>0.120</u> IN = <u>4<sup>13</sup>/<sub>16</sub></u> M MN = <u>0.120</u> M	<u>4<sup>9</sup>/<sub>16</sub></u> <u>4<sup>9</sup>/<sub>16</sub></u> <u>4<sup>9</sup>/<sub>16</sub></u> <u>0.116</u> IN = <u>4<sup>9</sup>/<sub>16</sub></u> M MN = <u>0.116</u> M	<u>4<sup>13</sup>/<sub>16</sub></u> <u>4<sup>14</sup>/<sub>16</sub></u> <u>4<sup>14</sup>/<sub>16</sub></u> <u>0.123</u> IN = <u>4<sup>13</sup>/<sub>16</sub></u> M MN = <u>0.1230</u> M
MN ADJ TO VERT:	<u>0.120</u> M	<u>0.116</u> M	<u>0.1234</u> M

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	PROGRAMMED REFPOS	FIELD POSITION	PROGRAMMED REFPOS	FIELD POSITION	PROGRAMMED REFPOS	FIELD POSITION
LAT	<u>39-12-30</u>	<u>39-12-22.64</u>	<u>39-12-30</u>	<u>39-12-22.48</u>	<u>39-12-30</u>	<u>39-12-22.81</u>
LONG	<u>123-10-30</u>	<u>123-10-33.42</u>	<u>123-10-30</u>	<u>123-10-33.20</u>	<u>123-10-30</u>	<u>123-10-33.62</u>
HT	<u>244.0</u>	<u>210.6</u>	<u>244.0</u>	<u>199.8</u>	<u>244.0</u>	<u>222.8</u>
PDOP	<u>3.6</u>	<u>-</u>	<u>4.8</u>	<u>-</u>	<u>4.0</u>	<u>-</u>
SVS TO TRACK LOCAL	<u>02,03,06,09</u> <u>11,12,13,14</u>	<u>02,03,06,09</u> <u>11,12,13,14</u>	<u>03,06,09,11</u> <u>12,13,14,16</u>			
TIME: SCHEDULED	<u>21:55</u>	<u>23:38</u>	<u>01:20</u>			
ACTUAL	<u>21:56</u>	<u>23:10</u>	<u>00:55</u>			
STOP	<u>22:55</u>	<u>20:38</u>	<u>02:20</u>			
	<u>22:55</u>	<u>00:38</u>	<u>02:20</u>			

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PAGE 1

a. Front

Figure F-5a. GPS Observation Log (Post-Survey)

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GPS DATA LOGGING SHEET

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	SESSION 1	SESSION 2	SESSION 3
ANT CABLE LENGTH	<u>100 ft</u>	<u>100 ft</u>	<u>35 ft</u>
POWER SUPPLY	<u>12V DC</u>	<u>12V DC</u>	<u>12V DC</u>
WEATHER CONDITIONS	<u>CLEAR, COOL</u> <u>45°</u>	<u>CLEAR, COOL</u> <u>40°</u>	<u>CLEAR, COOL</u> <u>40°</u>
MONUMENT TYPE	<u>"C" (SET IN PIER)</u>	<u>← SAME</u>	<u>← SAME</u>
EXACT STAMPING	<u>PIER 2 1953</u>	<u>← "</u>	<u>← "</u>
AGENCY CAST IN DISK	<u>COE</u>	<u>← "</u>	<u>← "</u>

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SESSION 1	SKETCH OF SITE SESSION 2	SESSION 3
	<p>← SAME</p>	<p>← SAME</p>

\*\*\*\*\*

Describe any abnormalities and/or problems encountered during the survey, include session number, time of occurrence and duration.

THE ANTENNA WAS MOUNTED DIRECTLY OVER PIER 2 WITH NO TRIPOD USED.  
ANTENNA HEIGHT WAS MEASURED VERTICALLY FROM GROUND PLANE TO BRASS DISK.

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PAGE 2

b. Back

Figure F-5b. GPS Observation Log (Post-Survey)

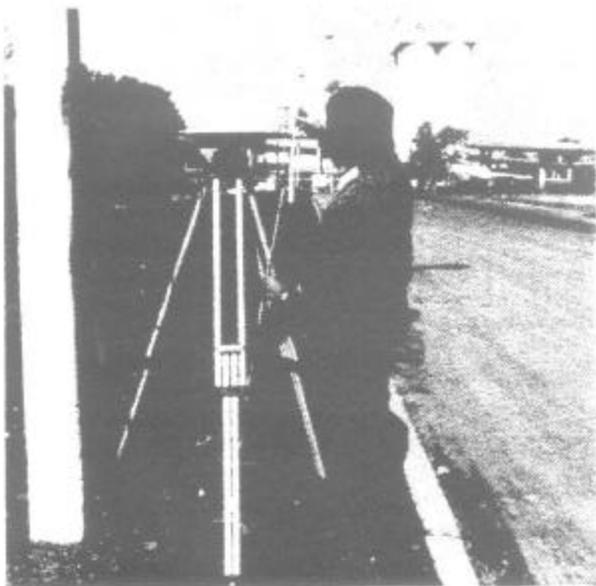


Figure F-6. Antenna Height Measurement

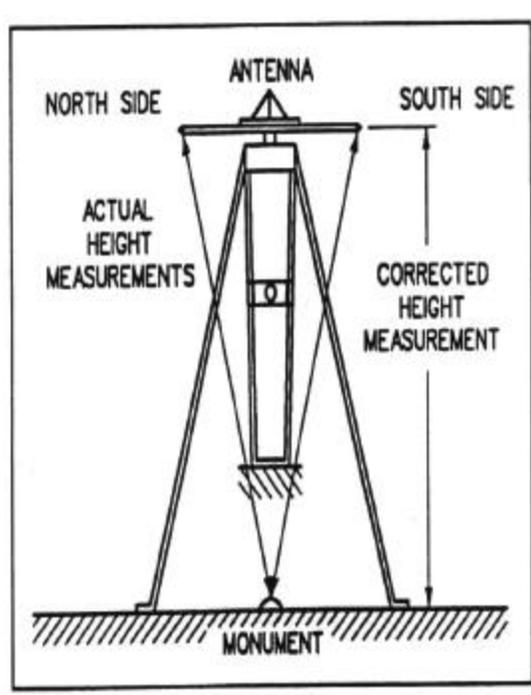


Figure F-7. Diagram of Antenna Setup

### F-3. Post-Processing Observation Data

All recorded observation data were downloaded from the receivers to 5.25" floppy discs. The downloading procedures detailed in the manufacturer's operating manuals were strictly adhered to.

*a.* Once the observation data was downloaded, preprocessing of data was performed. Preprocessing of data included checking the station names, antenna heights, latitude and longitude of the points, elevation of the points, as well as applying any required corrections. In general, most GPS processing software requires the antenna slope height be corrected to vertical at some point in the survey, usually during the preprocessing phase (consult receiver/software manufacturer guidelines for specifics).

*b.* The data for the Ukiah project was post-processed using Trimble software TRIMVEC Version 88.028--GPS Relative Positioning Solution), but in general, all post-processing software produces similar results. The observation data was processed in accordance with manufacturer guidelines (see Chapter 10 for further discussion on GPS baseline post-processing).

(1) An examination of the results reveals the following, which are produced in one form or another in other manufacturer's solution file formats:

- a--Listing of the filename
- b--Types of solutions (single, double, or triple difference)
- c--Satellite availability during the survey for each station occupied
- d--Ephemeris file used for solution formulation
- e--Type of satellite selection (manual or automatic)
- f--Elevation mask
- g--Minimum number of satellites used
- h--Meteorological data (pressure, temperature, humidity)
- i--Session time (date, time)
- j--Data logging time (start, stop)
- k--Station information: Location (latitude, longitude); Receiver serial number used; Antenna serial number used; ID number; Antenna height
- l--RMS
- m--Solution files: dx, dy, dz between station; Slope distance between station; dlatitude, dlongitude between station; Distance between station; dheight
- n--Epoch intervals
- o--Number of epochs

(2) The triple difference, double difference float, and double difference fix Trimble solutions of the baseline reductions for baseline 2014--2002 were computed. The fixed solution is shown in Figures F-8a through F-8d--annotated with the above conventions (a through o) provided as an explanation. A summary of all solutions is shown in Figure F-8e. The baseline formulations are reproduced from the Trimble Navigation TRIMVEC solution file.

c. In general, all GPS manufacturer data reduction software programs produce a summary of results once data has been reduced and a baseline formulated.

d. Although the Trimble summary solution file does specify that the integers were found, the RMS is OK, and FIXED solution is recommended, an analysis of the output prior to this conclusion in accordance with Chapter 10 would have revealed the following:

(1) With a baseline distance of 7000 m for the formulated baseline (baseline 1402) and from Table 10-2 (Fixed Solution Acceptance Criteria), the RMS must be less than  $(0.02+(0.004*d))$ . Using the formula  $(0.02+(0.004/d))$  from Table 10-2 with a distance (d) equal to 7 km, the equation is  $(0.02 + (0.004*7))$  and the RMS is approximately equal to 0.048. Therefore, the RMS is acceptable.

(2) With a baseline distance of 7000 m for the formulated baseline (baseline 1402) and from Table 10-3, the variance ratio must be more than 1.5. The fixed solution factor from the summary solution file is 18.9. Therefore, the fixed solution quality factor is acceptable.

(3) From Table 10-3, with a baseline length of 7 km for baseline 1402 (between 0 - 20 km), an acceptable RMS (small), an acceptable variance ratio (large), and an integer solution, the fixed solution should be acceptable.

e. All other formulated baselines for this survey were found to be acceptable.

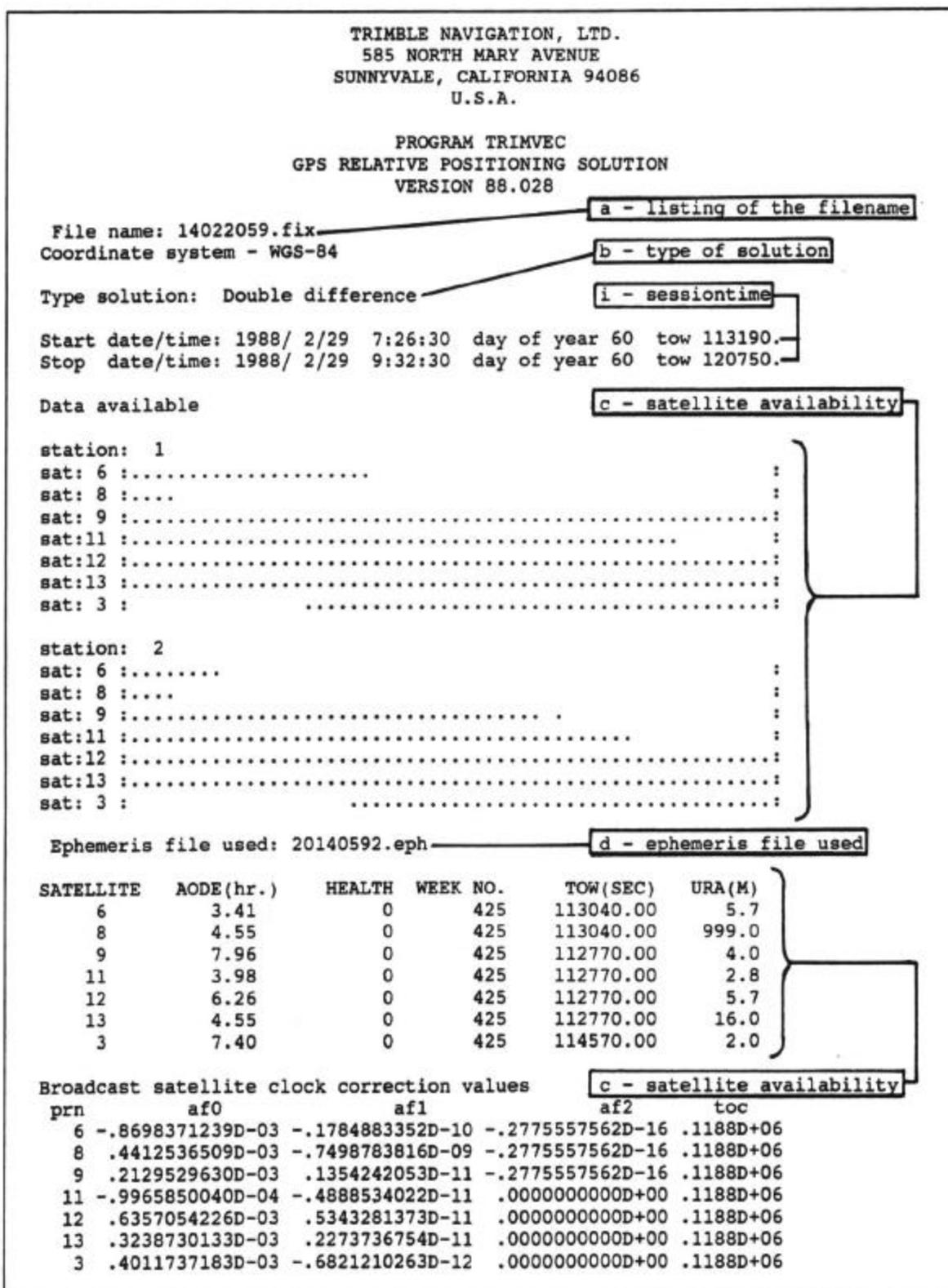


Figure F-8a. TRIMBLE Baseline Solution File (Ukiah Baseline 2014--2002)

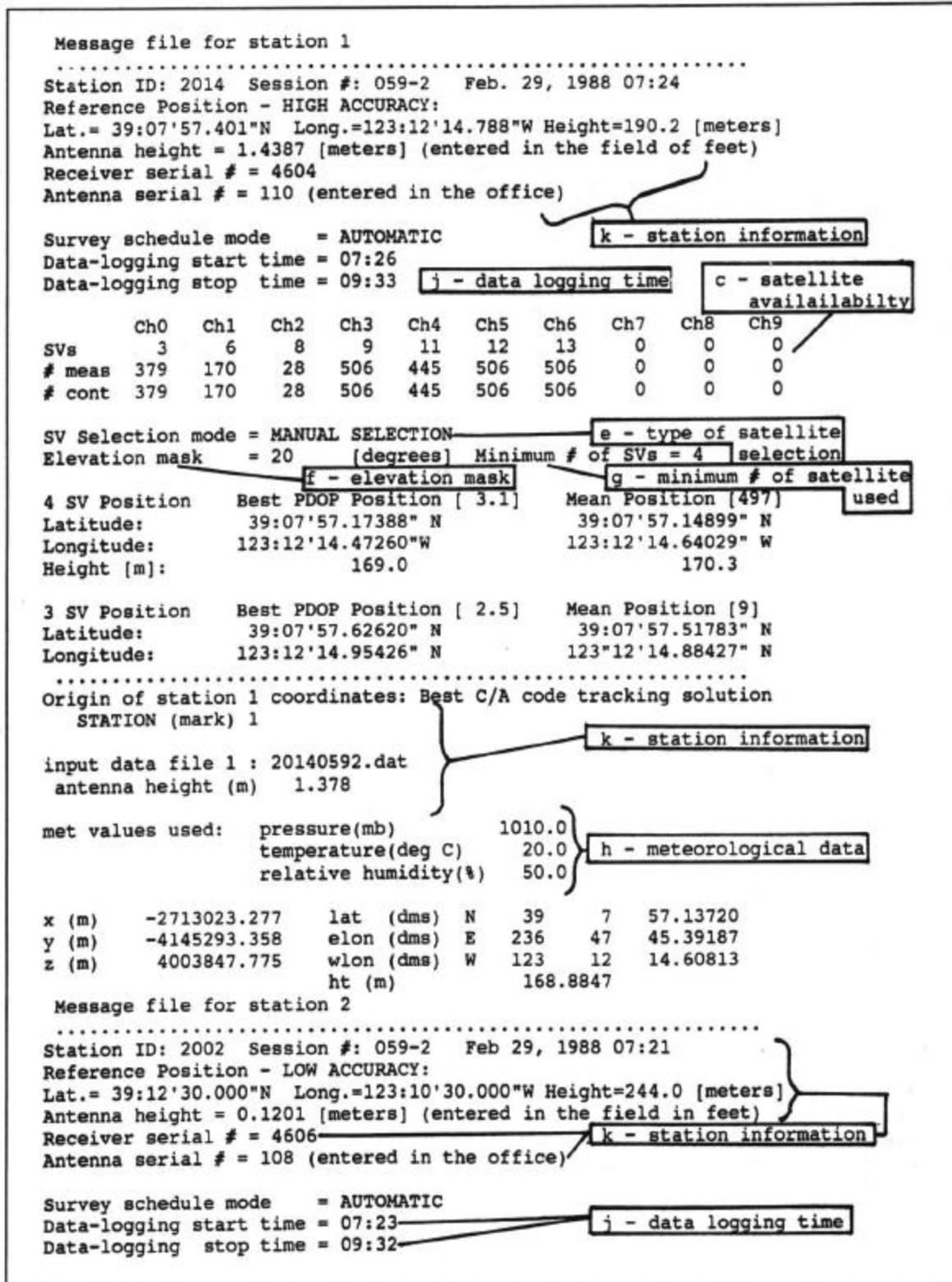


Figure F-8b. TRIMBLE Baseline Solution File (Ukiah Baseline 2014--2002)

```

      Ch0  Ch1  Ch2  Ch3  Ch4  Ch5  Ch6  Ch7  Ch8  Ch9
SVs      3    6    8    9   11   12   13    0    0    0
# meas   356  78   41  392  457  515  515    0    0    0
# cont   356  65   41  381  457  515  515    0    0    0

SV Selection mode = MANUAL SELECTION e - type of satellite selection
Elevation mask    = 20 [degrees] Minimum # of SVs = 4
f - elevation mask q - minimum # of satellite
4 SV Position Best PDOP Position [ 3.5] Mean Position [358] used
Latitude:       39:11'36.62852" N      39:11'36.67782" N
Longitude:      123:11'00.34360" W      123:11'00.44659" W
Height [m]:     251.8                    247.9
                k - station information
3 SV Position Best PDOP Position [ 2.5] Mean Position [157]
Latitude:       39:11'36.93995" N      39:11'36.76322" N
Longitude:      123:11'00.75300" W      123:11'00.69634" W
.....
STATION (mark) 2
input data file 1 : 20020592.dat k - station information
antenna height (m) .120
met values used:  pressure(mb)          1010.0
                  temperature(deg C)    20.0 h - meteorological data
                  relative humidity(%)  50.0
x (m) -2709224.271 lat (dms) N 39 11 36.66495
y (m) -4142739.345 elon (dms) E 236 48 59.56810
z (m)  4009144.592 wlon (dms) W 123 11 43.190
                  ht (m)                244.2339

slope distance (m) 7000.8355 sigma (m) .015
normal section azimuth (dms) 14 43 51.65
vertical angle (dms) 0 35 6.58

east(m) north(m) up(m) 1780.090 6770.367 71.498 m - solution file
Delta lat(dms) 0 3 39.52775
Delta lon(dms) 0 1 14.17622
Delta ht(m) 75.3491

Vector covariance matrix (m**2) :
                dx                dy
dx .785657836034D-04
dy .673839449077D-04 .723510872927D-03
dz -.843065752912D-04 -.504546156900D-03 .464958813305D-03
correlations:
dx dy dz trop bias1 bias2 bias3 bias4 bias5 bias6
bias7
dx 1.000
dy .283 1.000
dz -.680 -.870 1.000
trop .000 .000 .000 1.000
bias1 .000 .000 .000 .000 1.000
bias2 .000 .000 .000 .000 .000 1.000
bias3 .000 .000 .000 .000 .000 .000 1.000
bias4 .000 .000 .000 .000 .000 .000 .000 1.000
bias5 .000 .000 .000 .000 .000 .000 .000 .000 1.000
bias6 .000 .000 .000 .000 .000 .000 .000 .000 .000 1.000
bias7 .000 .000 .000 .000 .000 .000 .000 .000 .000 .000
1.000

```

Figure F-8c. TRIMBLE Baseline Solution File (Ukiah Baseline 2014--2002)

	Solution	Sigma	Sensitivity to 10 meter error in station 1 coordinates		
dx (m)	3799.006	.009	9.999	.000	-.002
dy (m)	2554.013	.027	-.001	10.000	-.001
dz (m)	.000	.000	.000	.000	10.000
trop (%)	.000	.000	.000	.000	.000
bias 1 (cycle)	.000	.000	.000	.000	.000
bias 2 (cycle)	.000	.000	.000	.000	.000
bias 3 (cycle)	.000	.000	.000	.000	.000
bias 4 (cycle)	.000	.000	.000	.000	.000
bias 5 (cycle)	.000	.000	.000	.000	.000
bias 6 (cycle)	.000	.000	.000	.000	.000
bias 7 (cycle)	.000	.000	.000	.000	.000
Results of integer bias search:					
	.0549	1.06578		1.36295	
	0		1		0
	0		0		0
	0		0		0
	0		0		0
	0		0		0
	0		0		0
Ratio sum-of-squares(2) to sum-of-squares(1)			18.87		
Interval between epochs (sec)			120		
Epoch increment			4		
Number of measurements used in solution			161		
Number of measurements rejected			56		
RMS (cycles)			.020		
Elevation mask (deg)			15.0		
Edit multiplier			3.5		
Modified Hopfield troposphere model used					
Best tracking C/A code positions					
Station 1					
Pdop	3.1				
x (m)	-2713023.862	lat (dms)	N 39 7	57.13720	
y (m)	-4145294.253	elon (dms)	E 236 47	45.39187	
z (m)	4003848.645	wlon (dms)	W 123 12	14.60813	
		ht (m)		170.2629	
clock offset(s) .43266808D-03					
freq offset(s/s) -.11042348D-08					
Code calibration(m)			Carrier calibration(m)		
1 - 2	.2520			.0012	
1 - 3	.0552			-.0006	
1 - 4	-.0249			-.0007	
1 - 5	.9292			-.0008	
1 - 6	-.2124			-.0010	
1 - 7	-.0181			.0005	
1 - 8	-.1875			-.0009	
1 - 9	-.1875			-.0012	
1 - 10	1.0630			-.0014	
Station 2					
Pdop	2.5				
x (m)	-2709227.033	lat (dms)	N 39 11	37.11338	
y (m)	-4142726.880	elon (dms)	E 236 48	59.18749	
z (m)	4009155.162	wlon (dms)	W 123 11	.81251	
		ht (m)		244.0000	
clock offset(s) .88584966D-03					
freq offset(s/s) .58827784D-09					
Code calibration(m)			Carrier calibration(m)		
1 - 2	.2021			.0007	
1 - 3	-.3682			-.0011	
1 - 4	-.4199			-.0010	
1 - 5	-.5342			-.0013	
1 - 6	-.5234			-.0011	
1 - 7	-.2754			-.0002	
1 - 8	-.6040			-.0014	
1 - 9	-.8003			-.0020	
1 - 10	-.6953			-.0017	

Figure F-8d. TRIMBLE Baseline Solution File (Ukiah Baseline 2014--2002)

-----  
TRIMVEC GPS RELATIVE POSITIONING SOLUTION SUMMARY: VERSION 88.028

SOLUTION OUTPUT FILE: a:14022059.fix

STATION 1: Station ID: 2014 Session No.: 059-2 Feb 29,1988  
07:24

Data-logging start time = 07:26 Data-logging stop time = 09:33

STATION 2: Station ID: 2002 Session #: 059-2 Feb 29,1988 07:21

Data-logging start time = 07:23 Data-logging stop time = 09:32

STATION COORDINATES:

Sta	Ant (m)	Latitude	Longitude	Hgt (m)
1	1.378	39:07'57.13720" N	123:12'14.60813" W	168.885
2 [TRP]	0.120	39:11'36.66538" N	123:11'00.43314" W	244.226
2 [FLT]	0.120	39:11'36.66472" N	123:11'00.43068" W	244.249
2 [FIX]	0.120	39:11'36.66495" N	123:11'00.43190" W	244.234

Origin of station 1 coordinates : Best C/A code tracking solution

SOLUTION SUMMARY:

Solution	dx (m)	dy (m)	dz (m)	dh (m)	RDOP
TRIPLE	3798.989	2554.042	5296.822	75.341	n/a
FLOAT	3799.022	2553.984	5296.821	75.365	n/a
FIXED	3799.006	2554.013	5296.817	75.349	n/a
FLT-FIX	0.016	-0.029	0.004	0.016	

Solution	Slope (m)	sig	Epochs/Rejected	Epoch int	Epoch inc
TRIPLE	7000.8406	[0.032]	168/ 1	150 (secs)	5 (epochs)
FLOAT	7000.8363	[0.036]	167/ 50	120 (secs)	4 (epochs)
FIXED	7000.8355	[0.015]	161/ 56	120 (secs)	4 (epochs)

Fixed solution quality factor: 18.9  
Fixed solution rms: 0.020 (cycles)  
Maximum float - fixed delta: 2.0 (cm)

Integers found, RMS is OK, FIXED solution recommended.  
-----

Figure F-8e. TRIMBLE Baseline Solution Summary File (Ukiah Baseline 2014--2002)

### F-4. Loop Closure

An approximate loop closure was done by following the procedures detailed in Chapter 10.

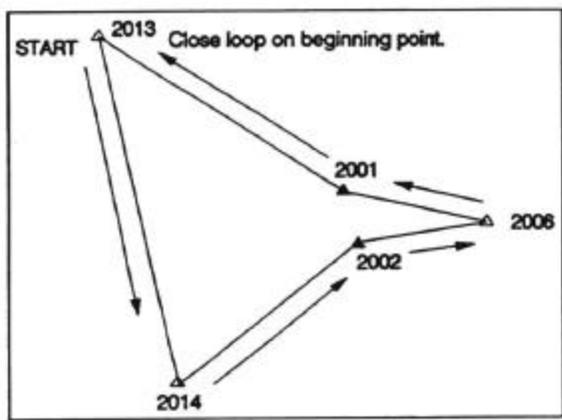


Figure F-9. Loop Closure (Ukiah)

The resulting calculations would proceed as shown in the following computation:

a. Follow Figure F-9, holding 2013 as the starting point.

b. Formulate a table similar to that shown in Chapter 10, where all values are taken from the GPS post-processed baseline formulations:

Baseline	$\Delta x$ (m)	$\Delta y$ (m)	$\Delta z$ (m)	Distance(m)
13142059.FIX 2013 -> 2014	-3367.429	-7891.019	-10410.673	13490.362
14021059.FIX 2014 -> 2002	3799.005	2554.018	5296.798	7000.823
02053056.FIX 2002 -> 2006	953.294	-748.319	-16.709	1212.035
06013056.FIX 2006 -> 2001	-666.617	1441.548	908.280	1829.593
01132059.FIX 2001 -> 2013	-718.244	4683.775	4222.288	6317.297

c. Sum up the  $\Delta x$ ,  $\Delta y$ ,  $\Delta z$ , and distance components:

$$\begin{aligned} \Sigma \Delta x \text{ components} &= \Delta x(2013 \rightarrow 2014) + \Delta x(2014 \rightarrow 2002) + \Delta x(2002 \rightarrow 2006) + \Delta x(2006 \rightarrow 2001) \\ &\quad + \Delta x(2001 \rightarrow 2013) = -3367.429 + 3799.005 + 953.294 + (-666.617) + (-718.244) = \underline{0.009} \end{aligned}$$

$$\begin{aligned} \Sigma \Delta y \text{ components} &= \Delta y(2013 \rightarrow 2014) + \Delta y(2014 \rightarrow 2002) + \Delta y(2002 \rightarrow 2006) + \Delta y(2006 \rightarrow 2001) \\ &\quad + \Delta y(2001 \rightarrow 2013) = -7891.019 + 2554.018 + (-748.319) + 1441.548 + 4643.775 = \underline{0.003} \end{aligned}$$

$$\begin{aligned} \Sigma \Delta z \text{ components} &= \Delta z(2013 \rightarrow 2014) + \Delta z(2014 \rightarrow 2002) + \Delta z(2002 \rightarrow 2006) + \Delta z(2006 \rightarrow 2001) \\ &\quad + \Delta z(2001 \rightarrow 2013) = -10410.673 + 5296.798 + (-16.709) + 908.280 + 4222.288 = \underline{-0.016} \end{aligned}$$

$$\begin{aligned}\Sigma\text{Distances} &= (2013\text{-}\rightarrow\text{2014}) + (2014\text{-}\rightarrow\text{2002}) + (2002\text{-}2006) + (2006\text{-}\rightarrow\text{2001}) + (2001\text{-}\rightarrow\text{2013}) \\ &= 13490.362 + 7000.823 + 1212.035 + 1829.593 + 6317.297 \qquad = \underline{29850.110}\end{aligned}$$

d. From Equation (10-1):

$$m = \text{sqrt} [ 0.009^2 + 0.003^2 + (-0.016)^2 ] = 0.018601075 \text{ or } 0.0186$$

Therefore, misclosure is approximately 0.0186 in 29850.110 m, or 1 part in 1,600,000.

## F-5. Final Adjustment

The program used for final adjustment of the Ukiah survey was the GEOLAB program (Version 1.82--1987). For an in depth technical discussion on GEOLAB, refer to the literature accompanying the GEOLAB software package. The following discussion on the GEOLAB adjustment of the Ukiah survey highlights some of the criteria used in the adjustment of a horizontal survey.

a. The input data file for a GEOLAB adjustment is called an "IOB" file. An IOB file can be created using a text editor program or with a GEOLAB option called "GPS Environment." An IOB file is specific to the GEOLAB adjustment software and may or may not be required by other least-square adjustment software (refer to Chapter 11 or the owner's manual). The GEOLAB Environment option takes GPS baseline solution files developed by most GPS manufacturers and automatically sets up an IOB file for adjustment.

b. The IOB input file generally consists of the following information:

- (1) Top Line. Title Record - usually a project name and an adjustment number.
- (2) Second Line. Options Record - this record specifies which GEOLAB options are to be activated for processing.
- (3) Third Line. Ellipsoid Specification Record - Prints ellipsoid parameters chosen in the Options Record or as chosen by the user.
- (4) Station Information Section. All stations must have their coordinates defined here. The coordinates must be given as ellipsoidal latitude, longitude, and orthometric height, or as Cartesian coordinates. In this section, stations are either held fixed or are to be adjusted. If stations are not held fixed, estimated coordinates are input.
- (5) Auxiliary Parameter Definition Record. The auxiliary parameter group definition record is optional, but can be used if GEOLAB is to solve for various scale, orientation, translation, or constant parameters. In the sample GEOLAB input, enough vertical and horizontal control is held fixed to solve for SCALE and ROTATION. Rotation is about the Cartesian X-axis, Y-axis, and Z-axis.
- (6) Observation Records Section. In the example GEOLAB input file, only GPS observations are entered. Each baseline is entered separately with the station name and Cartesian coordinate differences between the stations, which is the computed baseline. These can also be entered as  $\Delta x=0$ ,  $\Delta y=0$ ,  $\Delta z=0$ , for station 1 and the 3 D baseline for station 2. For example, baseline 1 would be entered as:

STATION	$\Delta x$	$\Delta y$	$\Delta z$
92 2001	0.000	0.000	0.000
92 2006	-666.617	1441.548	908.280

The correlation matrix elements from the baseline solution are also entered and the last line of the observation record is the standard deviation for  $\Delta x$ ,  $\Delta y$ , and  $\Delta z$ .

- c. Figure F-10 depicts GEOLAB input with annotations using the above convention.
- d. Once an IOB file containing parameters necessary to perform an adjustment has been completed, the adjustment can begin. The first step is to select the baselines needed for the adjustment. The baselines chosen must have been processed adequately, as detailed in Chapter 10, or as recommended by the GPS manufacturer.
- e. The example IOB file shown in Figure F-10 was adjusted as shown in Figure F-11.
- f. For the first adjustment (Figure F-11), one point was held fixed in 3D, producing a free adjustment). A free adjustment checks the internal consistency of a GPS survey--refer to Chapter 11 for further details.
- g. A second adjustment (not shown) can be done to check the existing network if these control points are directly tied together with GPS baselines. To do this with GEOLAB, the user must set up an IOB file with only the fixed control and the respective baselines connecting them. Hold fixed all control except one point, then perform the adjustment. Next, fix that control point and free one of the others, and keep repeating this procedure until all control points have been allowed to be checked against it's true position. If the position of one control point is "bad", that point can generally be omitted from the subsequent constrained adjustment or allowed to adjust with the other points.
- h. A final constrained adjustment (Figure F-12) should hold fixed all good horizontal and vertical control. Adjust and check the output as detailed in Chapter 11.

## F-6. Check of the Final Adjustment

After each adjustment was run, the 2-D and 1-D station (absolute) error ellipse for each adjusted point was reviewed (for further discussion on error ellipses and adjustments, refer to Chapter 11). These are listed as major semi-axis, minor semi-axis, major azimuth, and vertical. The sizes of the error ellipses listed in this portion of the GEOLAB adjustment are an indication of the internal consistency of the GPS survey. The smaller the size of the ellipse, the better the survey. The size of the ellipse will also generally become larger as the project size increases. In the constrained adjustment shown, the major semi-axis and minor semi-axis are of the mm level (0.0066 and 0.0048 mm for 2001 and 0.0062 and 0.0044 mm, respectively) - which is acceptable.

a. The 2-D and 1-D relative error ellipses and line accuracies (i.e. precision) between survey points were checked. These are listed as major semi-axis, minor semi-axis, major azimuth, vertical, spatial distance, and precision (as shown on labeled page 16 of the free adjustment and page 17 of the constrained adjustment). When checking these values, one should remember they are relative values. The relativity of points used in the adjustment can sometimes produce deceptive values, higher major semi-axis and minor semi-axis values: this may occur between points that are close together, but have not been tied together by a baseline. Because of the possibility of the production of deceptive results, the user must take special care when reviewing these values. In the constrained adjustment shown, the major semi-axis and minor semi-

axis are of the mm level (0.0045 and 0.0036 for the baseline 2001->2002). The project precision in parts per million (ppm) is also listed in this portion of the adjustment and should be checked.

*b.* The histograms in the GEOLAB adjustments were reviewed. The histogram is a visual representation of the standardized (normalized) residuals. The histogram shows whether the residuals are symmetrical about the mean residual, the total spread of values of the residuals, the frequencies of the different values, and how peaked or how flat the distribution of the residuals may be. A generally good looking histogram has data that, when graphed, is in the shape of a bell curve.

*c.* The free adjustment line accuracy precessions shown on Figure F-11 are the primary criteria used to evaluate the survey adequacy. The worst precision (4.182 ppm between 2001 and 2013) equates to 1:239,000. This far exceeds the required project accuracy (1:10,000). The relative line accuracy between 2001 and 2002 on the constrained adjustment was 3.846 ppm, or 1:260,000. This indicates excellent connections with existing control.

*d.* The variance factor shown on each adjustment is within acceptable limits (0.5 to 1.5). As such, it could be used to determine outlier limits for rejection of data, as explained in Chapter 11.

*e.* The residual corrections to each baseline component are shown on each adjustment. Special review is made of the Standardized Residuals, which one will find is approximately comparable to Normalized Residuals in GEOLAB software. None of the residuals were flagged (based on Tau Max testing) for exceeding tolerance.

*f.* The 3-D positional and relative confidence regions (ellipsoid) and 3-D line accuracy precessions are shown at the end of each adjustment. These statistics are not applicable for most USACE work.

*g.* Of all the output statistics, only the residuals, standardized residuals, relative 2-D/1-D line precessions, and variance factor have useful application for USACE work. The histograms, Chi-square tests, 3-D ellipsoid, etc. are useful only if one understands their derivation and application.

*h.* The results of the free and constrained adjustments in this example were not significantly different. This is usually not the case--typically, station/line accuracies degrade on the constrained adjustment.

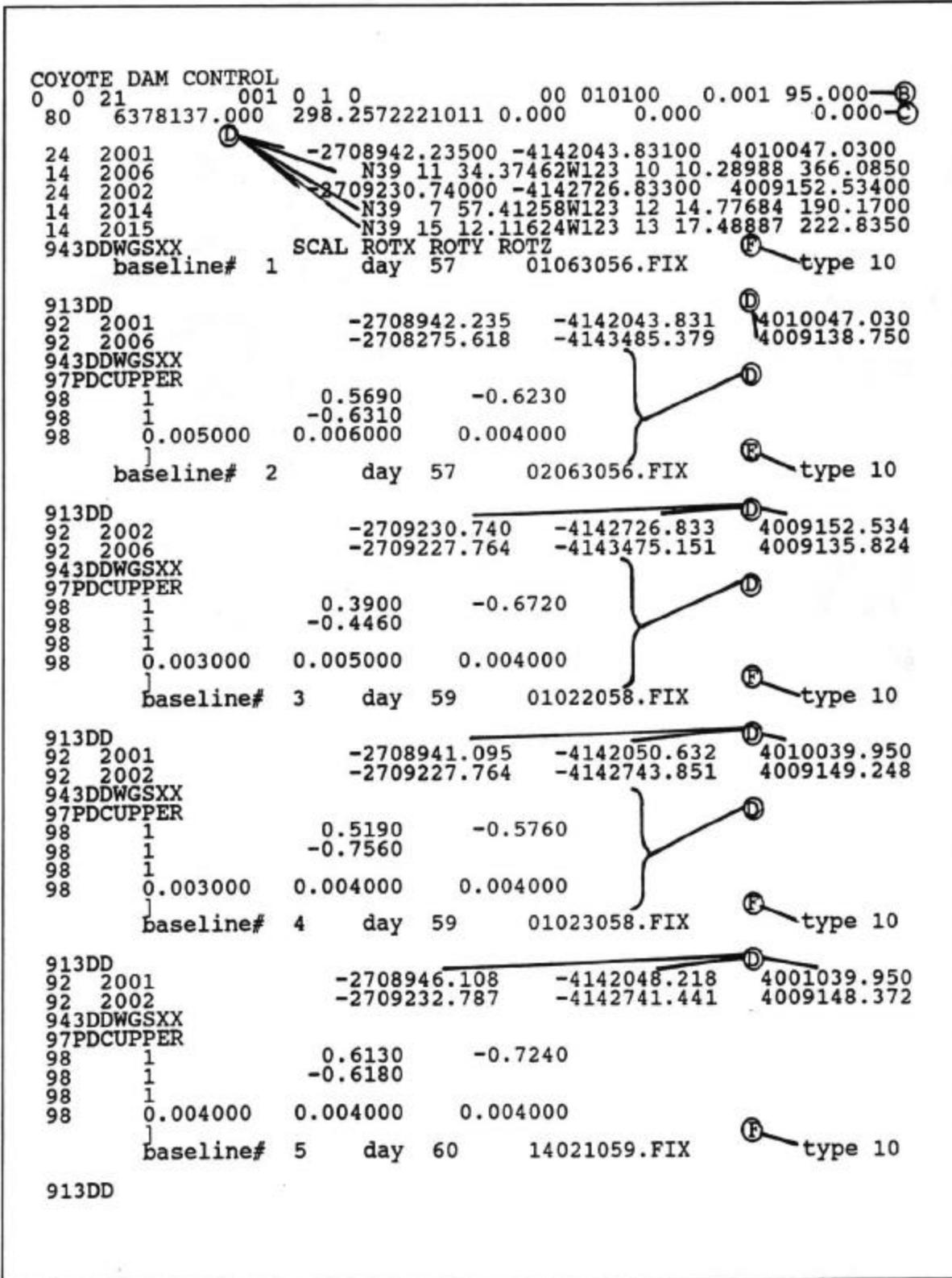


Figure F-10a. GEOLAB Input (Ukiah)

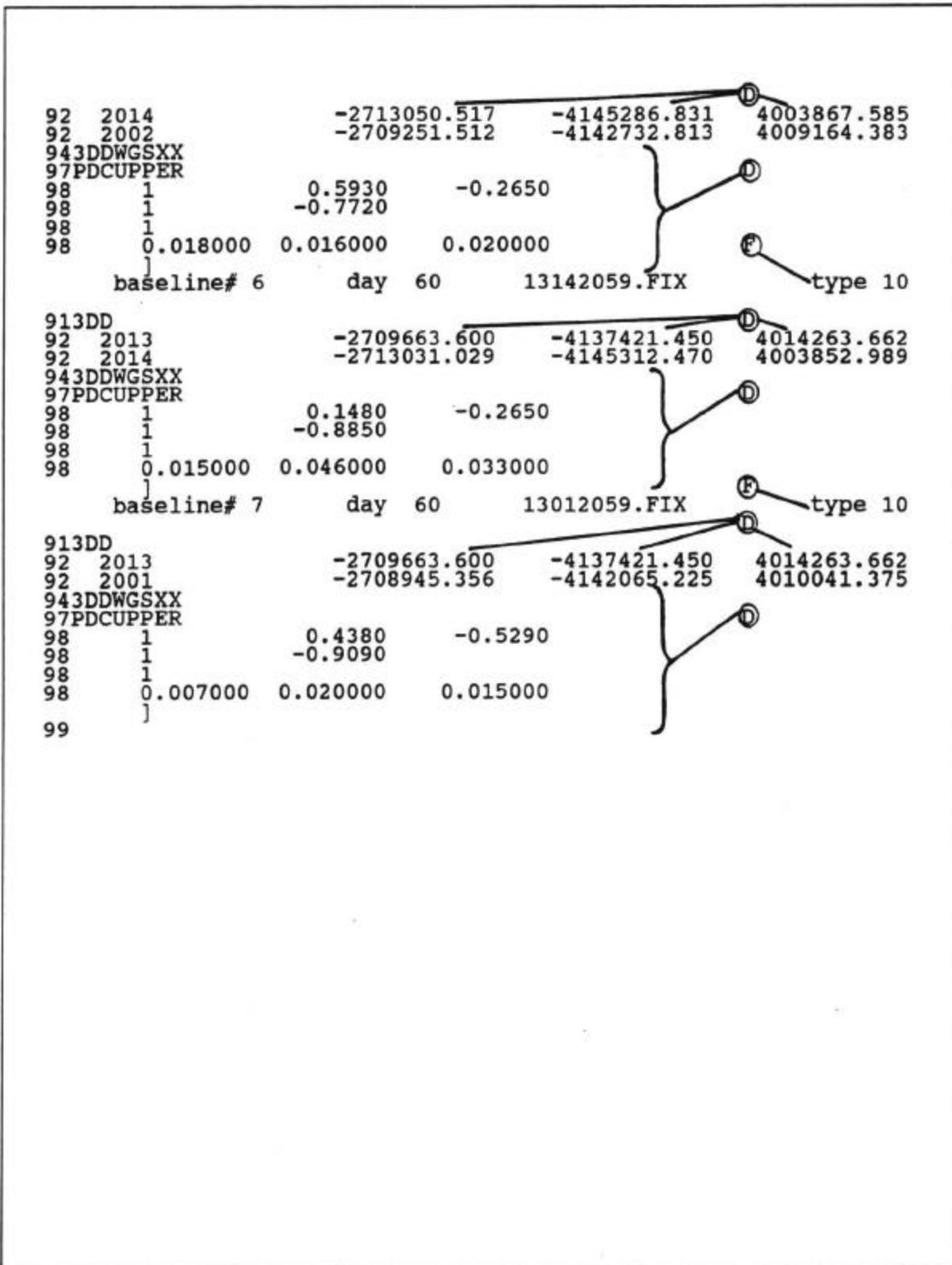


Figure F-10b. GEOLAB Input (Ukiah)

U.S. ARMY ENGINEER TOPOGRAPHIC LABORATORIES			
COYOTE DAM FREE ADJUSTMENT NAD-83			
A= 6378137.000 B= 6356752.314		X0= 0.000 Y0= 0.000 Z0= 0.000	
PREPARE: ASCII input file: <coyote_2.iob>.			
PREPARE successfully completed.			
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]		Page 0	
GETUP:			
PARAMETERS		OBSERVATIONS	
Description	Number	Description	Number
All Stations	5	Directions	0
Fixed Stations	1	Distances	0
Free 3-D Stations	4	Azimuths	0
Free 2-D Stations	0	Vertical Angles	0
Free 1-D Stations	0	Zenithal Angles	0
Coord. Parameters	12	Angles	0
Astro. Latitudes	0	Heights	0
Astro. Longitudes	0	Height Differences	0
Geoid Records	0	Auxiliary Params.	0
All Aux. Pars.	0	2-D Coords.	0
Direction Pars.	0	2-D Coord. Diffs.	0
Scale Parameters	0	3-D Coords.	0
Constant Pars.	0	3-D Coord. Diffs.	21
Rotation Pars.	0		
Translation Pars.	0		
Total Parameters	12	Total Observations	21
Degrees of Freedom = 9			
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]		Page 1	
SUMMARY OF SELECTED OPTIONS			
OPTION	SELECTION		
Computation Mode	Adjustment		
Linear Unit	Metre		
Maximum Iterations	2		
Confidence Regions Selected	All		
Confidence Region Dimensions	1-D, 2-D, and 3-D		
Print Input Station Data	On		
Variance Factor Knowledge	Known		
Confidence Level for Statistics	95.000		
Dual-Height Mode	Off		
Print Solution Vector	On All Iterations		
Printed Ellipsoidal Coordinates	5 Decimal Places		
Print Adjusted X, Y, Z	On		
Print Histograms	On		
Print Misclosures	On All Iterations		
Print Residuals	All		
Variance Factor Usage	Scale Confidence Regions		
Residual Rejection Criterion	Tau Max		
Angular Misclosure Limit Factor	10		
Linear Misclosure Limit Factor	10		
Convergence Criterion	0.001000		
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]		Page 2	

Figure F-11a. GEOLAB Adjustment Output (Free)

U.S. ARMY ENGINEER TOPOGRAPHIC LABORATORIES						
COYOTE DAM FREE ADJUSTMENT						
A= 6378137.000		B= 6356752.314		X0= 0.000	Y0= 0.000	Z0= 0.000
CODE IDENT.	DESCRIPTOR	INITIAL VALUES				
14 2006	ELLIPSOIDAL :	39 11 34.37462	-123 10 10.28988	336.0850		
	ASTRONOMIC :	39 11 34.37462	-123 10 10.28988	336.0850		
	GEOIDAL :	0 0 0.00000	0 0 0.00000	0.0000		
	CARTESIAN :	-2708280.4788	-4143494.7721	4009147.8933		
24 2001	ELLIPSOIDAL :	39 12 14.43422	-123 11 6.45941	243.8658		
	ASTRONOMIC :	39 12 14.43422	-123 11 6.45941	243.8658		
	GEOIDAL :	0 0 0.00000	0 0 0.00000	0.0000		
	CARTESIAN :	-2708942.2350	-4142043.8310	4010047.0300		
24 2002	ELLIPSOIDAL :	39 11 37.00656	-123 11 0.94286	243.8815		
	ASTRONOMIC :	39 11 37.00656	-123 11 0.94286	243.8815		
	GEOIDAL :	0 0 0.00000	0 0 0.00000	0.0000		
	CARTESIAN :	-2709230.7400	-4142726.8330	4009152.5340		
24 2014	ELLIPSOIDAL :	39 7 57.44196	-123 12 15.70589	188.7219		
	ASTRONOMIC :	39 7 57.44196	-123 12 15.70589	188.7219		
	GEOIDAL :	0 0 0.00000	0 0 0.00000	0.0000		
	CARTESIAN :	-2713050.5170	-4145286.8310	4003867.5850		
24 2013	ELLIPSOIDAL :	39 15 11.55819	-123 13 17.15396	220.5009		
	ASTRONOMIC :	39 15 11.55819	-123 13 17.15396	220.5009		
	GEOIDAL :	0 0 0.00000	0 0 0.00000	0.0000		
	CARTESIAN :	-2709663.6000	-4137421.4500	4014263.6620		
GETUP successfully completed.						
GeoLab - V1.82s, (C) 1985/86/87 BitWise Ideas Inc. [103207696]						Page 3
FORMEQ: NOTE 6: Reordering was done.						
AT	TO	OBS TYPE	OBSERVATION	APPROX. SIG.	MISCLOSURE	
2001	2006	3-D X-Coord Diff	666.6170	0.0037	-4.8608	
2001	2006	3-D Y-Coord Diff	-1441.5480	0.0045	-9.3931	
2001	2006	3-D Z-Coord Diff	-908.2800	0.0028	9.1433	
2002	2006	3-D X-Coord Diff	953.2950	0.0022	-3.0338	
2002	2006	3-D Y-Coord Diff	-748.3180	0.0044	-19.6211	
2002	2006	3-D Z-Coord Diff	-16.7100	0.0029	12.0693	
2001	2002	3-D X-Coord Diff	-286.6690	0.0024	-1.8360	
2001	2002	3-D Y-Coord Diff	-693.2190	0.0026	10.2170	
2001	2002	3-D Z-Coord Diff	-891.5890	0.0025	-2.9070	
2001	2002	3-D X-Coord Diff	-286.6790	0.0026	-1.8260	
2001	2002	3-D Y-Coord Diff	-693.2230	0.0030	10.2210	
2001	2002	3-D Z-Coord Diff	-891.5780	0.0026	-2.9180	
2014	2002	3-D X-Coord Diff	3799.0050	0.0129	20.7720	
2014	2002	3-D Y-Coord Diff	2554.0180	0.0101	5.9800	
2014	2002	3-D Z-Coord Diff	5296.7980	0.0113	-11.8490	
2013	2014	3-D X-Coord Diff	-3367.4290	0.0142	-19.4880	
2013	2014	3-D Y-Coord Diff	-7891.0200	0.0210	25.6390	
2013	2014	3-D Z-Coord Diff	-10410.6730	0.0147	14.5960	
2013	2001	3-D X-Coord Diff	718.2440	0.0059	3.1210	
2013	2001	3-D Y-Coord Diff	-4643.7750	0.0083	21.3940	
2013	2001	3-D Z-Coord Diff	-4222.2870	0.0059	5.6550	
FORMEQ successfully completed.						
GeoLab - V1.82s, (C) 1985/86/87 BitWise Ideas Inc. [103207696]						Page 4

Figure F-11b. GEOLAB Adjustment Output (Free)

```

-----
                        U.S. ARMY ENGINEER TOPOGRAPHIC LABORATORIES
                        COYOTE DAM      FREE ADJUSTMENT
A= 6378137.000 B= 6356752.314 X0=      0.000 Y0=      0.000 Z0=      0.000
-----
SOLVE:      Solution (Iteration Count = 1):
CODE IDENT. TYPE          INITIAL          DX          UPDATED
-----
24 2001     LATITUDE    39 12 14.43422      0.01413      39 12 14.44836
24 2001     LONGITUDE  -123 11 6.45941      0.04476     -123 11 6.41465
24 2001     HEIGHT          243.86577      13.93969      257.80546

24 2002     LATITUDE    39 11 37.00656     -0.06729      39 11 36.93927
24 2002     LONGITUDE  -123 11 0.94286      0.34171     -123 11 0.60115
24 2002     HEIGHT          243.88154      21.63376      265.51530

24 2014     LATITUDE    39  7 57.44196     -0.02938      39  7 57.41258
24 2014     LONGITUDE  -123 12 15.70589      0.92905     -123 12 14.77684
24 2014     HEIGHT          188.72193      1.44519      190.16712

24 2013     LATITUDE    39 15 11.55819      0.55805      39 15 12.11624
24 2013     LONGITUDE  -123 13 17.15396     -0.33491     -123 13 17.48887
24 2013     HEIGHT          220.50094      2.33476      222.83570
SOLVE successfully completed.
-----
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]      Page      5
-----
FORMEQ:      FORMEQ successfully completed.
-----
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]      Page      6
-----
SOLVE:      Adjusted Values (Iteration Count = 2):
CODE IDENT. TYPE          INITIAL          DX          ADJUSTED
-----
14 2006     LATITUDE    39 11 34.37462          FIXED
14 2006     LONGITUDE  -123 10 10.28988          FIXED
14 2006     HEIGHT          336.08500          FIXED

24 2001     LATITUDE    39 12 14.44836     -0.00000      39 12 14.44836
24 2001     LONGITUDE  -123 11 6.41465     -0.00000     -123 11 6.41465
24 2001     HEIGHT          257.80546     -0.00000      257.80546

24 2002     LATITUDE    39 11 36.93927      0.00000      39 11 36.93927
24 2002     LONGITUDE  -123 11 0.60115     -0.00000     -123 11 0.60115
24 2002     HEIGHT          265.51530      0.00001      265.51530

24 2014     LATITUDE    39  7 57.41258     -0.00000      39  7 57.41258
24 2014     LONGITUDE  -123 12 14.77684     -0.00000     -123 12 14.77684
24 2014     HEIGHT          190.16712      0.00004      190.16716

24 2013     LATITUDE    39 15 12.11624     -0.00000      39 15 12.11624
24 2013     LONGITUDE  -123 13 17.48887     -0.00000     -123 13 17.48887
24 2013     HEIGHT          222.83570      0.00003      222.83573
-----
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]      Page      7
-----
                        Adjusted Cartesian Coordinates:
CODE IDENT. X-COORDINATE      Y-COORDINATE      Z-COORDINATE
-----
24 2001     -2708947.0978     -4142053.2284     4010056.1788
24 2002     -2709233.7714     -4142746.4510     4009164.5970
24 2014     -2713032.7730     -4145300.4675     4003867.7943
24 2013     -2709665.3421     -4137409.4529     4014278.4662
SOLVE successfully completed.
-----
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]      Page      8

```

Figure F-11c. GEOLAB Adjustment Output (Free)

```

-----
                U.S. ARMY ENGINEER TOPOGRAPHIC LABORATORIES
                COYOTE DAM      FREE ADJUSTMENT
A= 6378137.000 B= 6356752.314 X0= 0.000 Y0= 0.000 Z0= 0.000
-----
INVERT:      INVERT successfully completed.
-----
GeoLab - V1.82s, (C) 1985/86/87 BitWise Ideas Inc. [103207696]      Page 9
-----
RESID:
STATION  3-D COORD DIFFS      STD.DEV.  RESIDUAL  STD.DEV.  STAN.RES.
-----
2001      -2708942.2350
           -4142043.8310
           4010047.0300
2006      -2708275.6180      0.0050      0.0020      0.0040      0.4913
           -4143485.3790      0.0060      0.0043      0.0044      0.9722
           4009138.7500      0.0040      -0.0055      0.0026      -2.1131
=====
                        End of Observation Set =====
2002      -2709230.7400
           -4142726.8330
           4009152.5340
2006      -2708277.4450      0.0030      -0.0024      0.0015      -1.5684
           -4143475.1510      0.0050      -0.0031      0.0031      -1.0050
           4009135.8240      0.0040      0.0063      0.0026      2.4021
=====
                        End of Observation Set =====
2001      -2708941.0950
           -4142050.6320
           4010040.8370
2002      -2709227.7640      0.0030      -0.0046      0.0020      -2.2695
           -4142743.8510      0.0040      -0.0036      0.0031      -1.1723
           4009149.2480      0.0040      0.0072      0.0032      2.2790
=====
                        End of Observation Set =====
2001      -2708946.1080
           -4142048.2180
           4010039.9500
2002      -2709232.7870      0.0040      0.0054      0.0033      1.6114
           -4142741.4410      0.0040      0.0004      0.0031      0.1290
           4009148.3720      0.0040      -0.0038      0.0032      -1.1996
=====
                        End of Observation Set =====
2014      -2713050.5170
           -4145286.8310
           4003867.5850
2002      -2709251.5120      0.0180      -0.0034      0.0132      -0.2586
           -4142732.8130      0.0160      -0.0015      0.0077      -0.1983
           4009164.3830      0.0200      0.0047      0.0129      0.3661
=====
                        End of Observation Set =====
2013      -2709663.6000
           -4137421.4500
           4014263.6620
2014      -2713031.0290      0.0150      -0.0019      0.0092      -0.2019
           -4145312.4700      0.0460      0.0054      0.0407      0.1332
           4003852.9890      0.0330      0.0011      0.0275      0.0389
-----
GeoLab - V1.82s, (C) 1985/86/87 BitWise Ideas Inc. [103207696]      Page 10
-----
RESID:
STATION  3-D COORD DIFFS      STD.DEV.  RESIDUAL  STD.DEV.  STAN.RES.
-----
=====
                        End of Observation Set =====
2013      -2709663.6000
           -4137421.4500
           4014263.6620
2001      -2708945.3560      0.0070      0.0003      0.0021      0.1596
           -4142065.2250      0.0200      -0.0005      0.0076      -0.0670
           4010041.3750      0.0150      -0.0004      0.0055      -0.0743
=====
                        End of Observation Set =====
-----
GeoLab - V1.82s, (C) 1985/86/87 BitWise Ideas Inc. [103207696]      Page 11

```

Figure F-11d. GEOLAB Adjustment Output (Free)

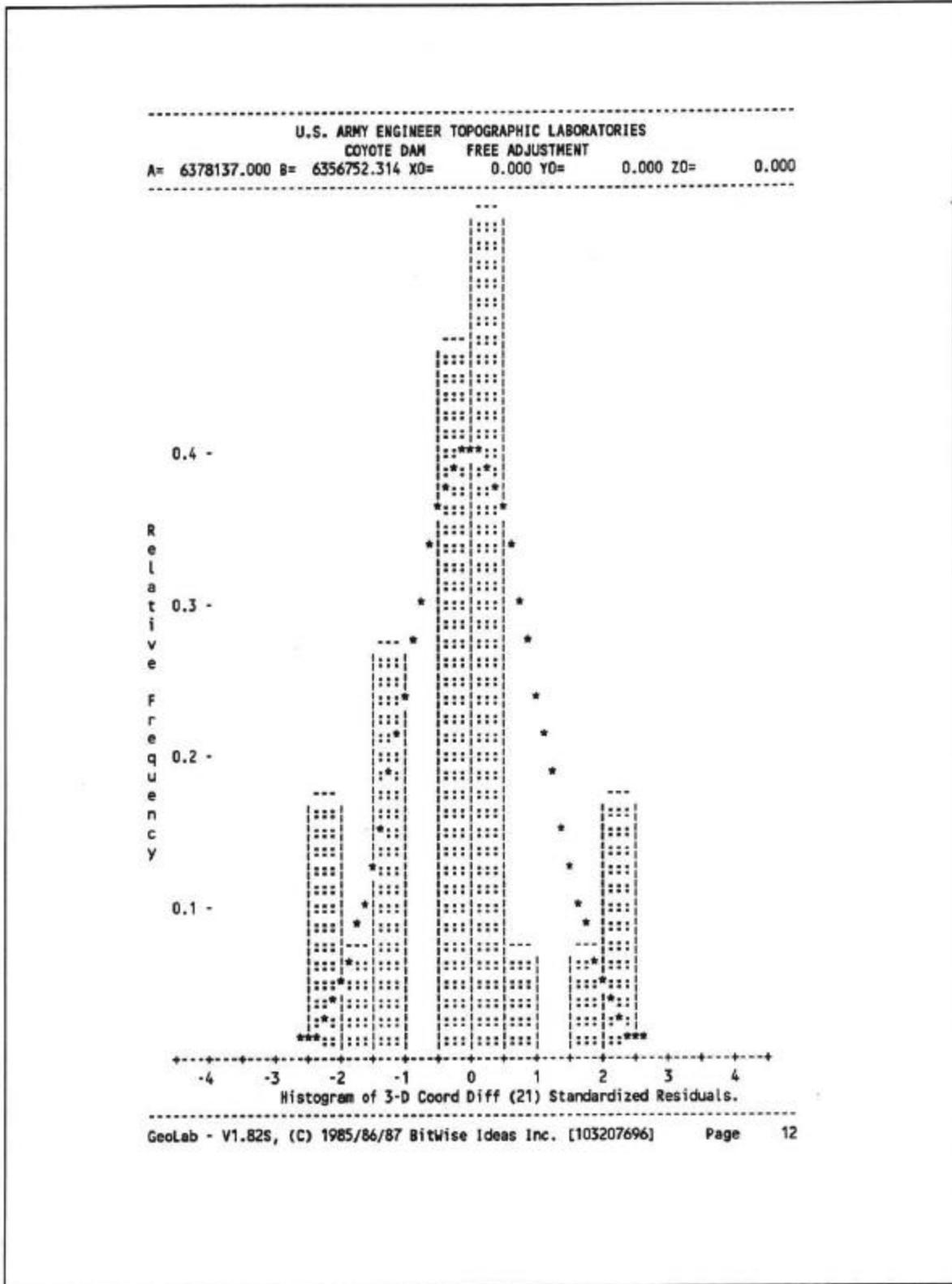


Figure F-11e. GEOLAB Adjustment Output (Free)

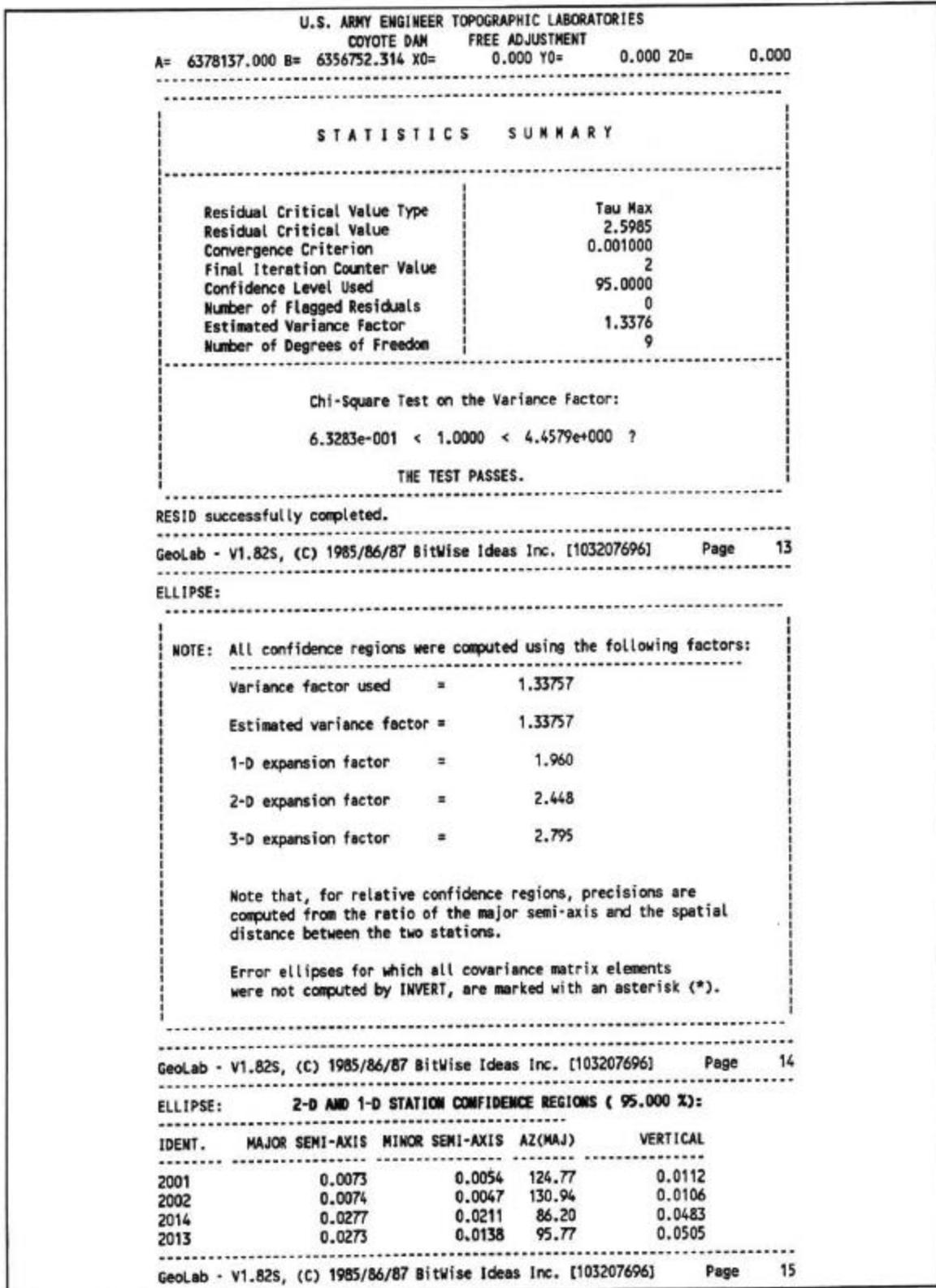


Figure F-11f. GEOLAB Adjustment Output (Free)

-----  
 U.S. ARMY ENGINEER TOPOGRAPHIC LABORATORIES  
 COYOTE DAM FREE ADJUSTMENT  
 A= 6378137.000 B= 6356752.314 X0= 0.000 Y0= 0.000 Z0= 0.000  
 -----

ELLIPSE: 2-D AND 1-D RELATIVE STATION CONFIDENCE REGIONS ( 95.000 %):

FROM	TO	MAJ.SEMI	MIN.SEMI	AZ(MAJ)	VERTICAL	SPATIAL DIST.	PRECISION
2001	2002	0.0045	0.0038	105.27	0.0082	1165.1856	3.881 PPM
2001	2014	0.0272	0.0204	84.07	0.0475	8095.2706	3.363 PPM
2001	2013	0.0264	0.0125	94.67	0.0494	6317.2966	4.182 PPM
2002	2014	0.0271	0.0203	83.67	0.0473	7000.8237	3.871 PPM
2002	2013	0.0267	0.0130	94.73	0.0499	7404.1516	3.612 PPM
2014	2013	0.0359	0.0216	91.44	0.0607	13490.3592	2.665 PPM

-----  
 Geolab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696] Page 16  
 -----

ELLIPSE: 3-D STATION CONFIDENCE REGIONS ( 95.000 %):

IDENT.	MAJOR SEMI-AXIS	MEDIUM SEMI-AXIS	MINOR SEMI-AXIS
2001	0.0161	0.0082	0.0059
	A=180.0 V= 80.4	A=298.9 V= 4.7	A= 29.6 V= 8.3
2002	0.0152	0.0082	0.0054
	A=161.8 V= 79.9	A=307.9 V= 8.4	A= 38.7 V= 5.6
2014	0.0690	0.0316	0.0237
	A=345.0 V= 86.1	A= 85.7 V= 0.7	A=175.8 V= 3.8
2013	0.0754	0.0219	0.0157
	A= 94.5 V= 72.1	A=279.0 V= 17.9	A=188.6 V= 1.3

-----  
 Geolab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696] Page 17  
 -----

ELLIPSE: 3-D RELATIVE STATION CONFIDENCE REGIONS ( 95.000 %):

FROM	TO	MAJOR-SEMI	MED.-SEMI	MINOR-SEMI	SPATIAL DIST.	PRECISION
2001	2002	0.0117	0.0051	0.0044	1165.1856	10.011 PPM
		A= 0 V=90 A= 90 V= 0 A= 0 V= 0				
2001	2014	0.0679	0.0311	0.0228	8095.2706	8.392 PPM
		A=347 V=86 A= 84 V= 1 A=174 V= 4				
2001	2013	0.0739	0.0201	0.0142	6317.2966	11.704 PPM
		A= 93 V=72 A=279 V=18 A=188 V= 2				
2002	2014	0.0677	0.0309	0.0226	7000.8237	9.666 PPM
		A=342 V=85 A= 83 V= 1 A=173 V= 4				
2002	2013	0.0745	0.0210	0.0148	7404.1516	10.064 PPM
		A= 93 V=72 A=278 V=18 A=188 V= 1				
2014	2013	0.0887	0.0363	0.0245	13490.3592	6.577 PPM
		A= 85 V=76 A=275 V=14 A=185 V= 2				

ELLIPSE successfully completed.

-----  
 Geolab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696] Page 18  
 -----

Figure F-11g. GEOLAB Adjustment Output (Free)

U.S. ARMY ENGINEER TOPOGRAPHIC LABORATORIES			
COYOTE DAM CONSTRAINED ADJUSTMENT NAD-83			
A= 6378137.000 B= 6356752.314 X0= 0.000 Y0= 0.000 Z0= 0.000			
PREPARE: ASCII input file: <coyote_1.iob>.			
PREPARE successfully completed.			
Geolab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]			Page 0
GETUP:			
PARAMETERS		OBSERVATIONS	
Description	Number	Description	Number
All Stations	5	Directions	0
Fixed Stations	3	Distances	0
Free 3-D Stations	2	Azimuths	0
Free 2-D Stations	0	Vertical Angles	0
Free 1-D Stations	0	Zenithal Angles	0
Coord. Parameters	6	Angles	0
Astro. Latitudes	0	Heights	0
Astro. Longitudes	0	Height Differences	0
Geoid Records	0	Auxiliary Params.	0
All Aux. Pars.	4	2-D Coords.	0
Direction Pars.	0	2-D Coord. Diffs.	0
Scale Parameters	1	3-D Coords.	0
Constant Pars.	0	3-D Coord. Diffs.	21
Rotation Pars.	3		
Translation Pars.	0		
-----		-----	
Total Parameters	10	Total Observations	21
Degrees of Freedom =		11	
Geolab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]			Page 1
GETUP: SUMMARY OF SELECTED OPTIONS			
OPTION	SELECTION		
Computation Mode	Adjustment		
Linear Unit	Metre		
Maximum Iterations	2		
Confidence Regions Selected	All		
Confidence Region Dimensions	1-D, 2-D, and 3-D		
Print Input Station Data	On		
Variance Factor Knowledge	Known		
Confidence Level for Statistics	95.000		
Dual-Weight Mode	Off		
Print Solution Vector	On All Iterations		
Printed Ellipsoidal Coordinates	5 Decimal Places		
Print Adjusted X, Y, Z	On		
Print Histograms	On		
Print Misclosures	On All Iterations		
Print Residuals	All		
Variance Factor Usage	Scale Confidence Regions		
Residual Rejection Criterion	Tau Max		
Angular Misclosure Limit Factor	10		
Linear Misclosure Limit Factor	10		
Convergence Criterion	0.001000		
Geolab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]			Page 2

Figure F-12a. GEOLAB Adjustment Output (Constrained)

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-----
                U.S. ARMY ENGINEER TOPOGRAPHIC LABORATORIES
                COYOTE DAM ADJUSTMENT NAD-83
A= 6378137.000 B= 6356752.314 X0= 0.000 Y0= 0.000 Z0= 0.000
-----
CODE IDENT.  DESCRIPTOR  INITIAL VALUES
-----
14 2006
    ELLIPSOIDAL : 39 11 34.37462 -123 10 10.28988      336.0850
    ASTRONOMIC  : 39 11 34.37462 -123 10 10.28988      336.0850
    GEODIAL     : 0 0 0.00000 0 0 0.00000              0.0000
    CARTESIAN   : -2708280.4788 -4143494.7721      4009147.8933

14 2013
    ELLIPSOIDAL : 39 15 12.11624 -123 13 17.48887      222.8350
    ASTRONOMIC  : 39 15 12.11624 -123 13 17.48887      222.8350
    GEODIAL     : 0 0 0.00000 0 0 0.00000              0.0000
    CARTESIAN   : -2709665.3418 -4137409.4525      4014278.4657

14 2014
    ELLIPSOIDAL : 39 7 57.41258 -123 12 14.77684       190.1700
    ASTRONOMIC  : 39 7 57.41258 -123 12 14.77684       190.1700
    GEODIAL     : 0 0 0.00000 0 0 0.00000              0.0000
    CARTESIAN   : -2713032.7742 -4145300.4693      4003867.7960

24 2001
    ELLIPSOIDAL : 39 12 14.43422 -123 11 6.45941        243.8658
    ASTRONOMIC  : 39 12 14.43422 -123 11 6.45941        243.8658
    GEODIAL     : 0 0 0.00000 0 0 0.00000              0.0000
    CARTESIAN   : -2708942.2350 -4142043.8310      4010047.0300

24 2002
    ELLIPSOIDAL : 39 11 37.00656 -123 11 0.94286        243.8815
    ASTRONOMIC  : 39 11 37.00656 -123 11 0.94286        243.8815
    GEODIAL     : 0 0 0.00000 0 0 0.00000              0.0000
    CARTESIAN   : -2709230.7400 -4142726.8330      4009152.5340

94 WGSXX
    300 SCAL : 0.00000
    300 ROTX : 0.00000
    300 ROTY : 0.00000
    300 ROTZ : 0.00000
GETUP successfully completed.
-----
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696] Page 3
FORMEQ: NOTE 6: Reordering was done.
AT TO OBS TYPE OBSERVATION APPROX.SIG. MISCLOSURE
-----
2001 2006 3-D X-Coord Diff 666.6170 0.0037 -4.8608
2001 2006 3-D Y-Coord Diff -1441.5480 0.0045 -9.3931
2001 2006 3-D Z-Coord Diff -908.2800 0.0028 9.1433
2002 2006 3-D X-Coord Diff 953.2950 0.0022 -3.0338
2002 2006 3-D Y-Coord Diff -748.3180 0.0044 -19.6211
2002 2006 3-D Z-Coord Diff -16.7100 0.0029 12.0693
2001 2002 3-D X-Coord Diff -286.6690 0.0024 -1.8360
2001 2002 3-D Y-Coord Diff -693.2190 0.0026 10.2170
2001 2002 3-D Z-Coord Diff -891.5890 0.0025 -2.9070
2001 2002 3-D X-Coord Diff -286.6790 0.0026 -1.8260
2001 2002 3-D Y-Coord Diff -693.2230 0.0030 10.2210
2001 2002 3-D Z-Coord Diff -891.5780 0.0026 -2.9180
2014 2002 3-D X-Coord Diff 3799.0050 0.0129 3.0292
2014 2002 3-D Y-Coord Diff 2554.0180 0.0101 19.6183
2014 2002 3-D Z-Coord Diff 5296.7980 0.0113 -12.0600
2013 2001 3-D X-Coord Diff 718.2440 0.0059 4.8628
2013 2001 3-D Y-Coord Diff -4643.7750 0.0083 9.3965
2013 2001 3-D Z-Coord Diff -4222.2870 0.0059 -9.1487
FORMEQ successfully completed.
-----
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696] Page 4

```

Figure F-12b. GEOLAB Adjustment Output (Constrained)

```

-----
                U.S. ARMY ENGINEER TOPOGRAPHIC LABORATORIES
                COYOTE DAM ADJUSTMENT NAD-83
A= 6378137.000 B= 6356752.314 X0= 0.000 Y0= 0.000 Z0= 0.000
-----
SOLVE:      Solution (Iteration Count = 1):
CODE IDENT. TYPE          INITIAL          DX          UPDATED
-----
24 2001     LATITUDE   39 12 14.43422    0.01413    39 12 14.44836
24 2001     LONGITUDE -123 11 6.45941    0.04476   -123 11 6.41465
24 2001     HEIGHT          243.86577    13.93968          257.80545

24 2002     LATITUDE   39 11 37.00656   -0.06729    39 11 36.93927
24 2002     LONGITUDE -123 11 0.94286    0.34171   -123 11 0.60115
24 2002     HEIGHT          243.88154    21.63406          265.51561

94 WGSXX     3DD SCAL          0.00000    -0.00161          -0.00161
94 WGSXX     3DD ROTX          0.00000    0.03270           0.03270
94 WGSXX     3DD ROTY          0.00000   -0.06406          -0.06406
94 WGSXX     3DD ROTZ          0.00000   -0.04338          -0.04338
SOLVE successfully completed.
-----
Geolab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]      Page 5
-----
FORMER:      FORMER successfully completed.
-----
Geolab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]      Page 6
-----
SOLVE:      Adjusted Values (Iteration Count = 2):
CODE IDENT. TYPE          INITIAL          DX          ADJUSTED
-----
14 2006     LATITUDE   39 11 34.37462          FIXED
14 2006     LONGITUDE -123 10 10.28988          FIXED
14 2006     HEIGHT          336.08500          FIXED

14 2013     LATITUDE   39 15 12.11624          FIXED
14 2013     LONGITUDE -123 13 17.48887          FIXED
14 2013     HEIGHT          222.83500          FIXED

14 2014     LATITUDE   39 7 57.41258          FIXED
14 2014     LONGITUDE -123 12 14.77684          FIXED
14 2014     HEIGHT          190.17000          FIXED

24 2001     LATITUDE   39 12 14.44836    0.00000    39 12 14.44836
24 2001     LONGITUDE -123 11 6.41465    0.00000   -123 11 6.41465
24 2001     HEIGHT          257.80545   -0.00000          257.80545

24 2002     LATITUDE   39 11 36.93927    0.00000    39 11 36.93927
24 2002     LONGITUDE -123 11 0.60115   -0.00000   -123 11 0.60115
24 2002     HEIGHT          265.51561    0.00000          265.51561

94 WGSXX     3DD SCAL          -0.00161    0.00000          -0.00161
94 WGSXX     3DD ROTX          0.03270   -0.00000           0.03270
94 WGSXX     3DD ROTY          -0.06406    0.00000          -0.06406
94 WGSXX     3DD ROTZ          -0.04338    0.00000          -0.04338
-----
Geolab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]      Page 7

```

Figure F-12c. GEOLAB Adjustment Output (Constrained)

U.S. ARMY ENGINEER TOPOGRAPHIC LABORATORIES  
COYOTE DAM ADJUSTMENT NAD-83

A= 6378137.000 B= 6356752.314 X0= 0.000 Y0= 0.000 Z0= 0.000

-----  
Adjusted Cartesian Coordinates:  
-----

CODE IDENT.	X-COORDINATE	Y-COORDINATE	Z-COORDINATE
24 2001	-2708947.0978	-4142053.2284	4010056.1788
24 2002	-2709233.7715	-4142746.4512	4009164.5972

SOLVE successfully completed.

-----  
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696] Page 8  
-----

INVERT: INVERT successfully completed.

-----  
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696] Page 9  
-----

RESID:

STATION	3-D COORD DIFFS	STD.DEV.	RESIDUAL	STD.DEV.	STAN.RES.
2001	-2708942.2350				
	-4142043.8310				
	4010047.0300				
2006	-2708275.6180	0.0050	0.0020	0.0041	0.4865
	-4143485.3790	0.0060	0.0043	0.0045	0.9530
	4009138.7500	0.0040	-0.0055	0.0026	-2.1060
===== End of Observation Set =====					
2002	-2709230.7400				
	-4142726.8330				
	4009152.5340				
2006	-2708277.4450	0.0030	-0.0024	0.0016	-1.5309
	-4143475.1510	0.0050	-0.0031	0.0032	-0.9650
	4009135.8240	0.0040	0.0063	0.0026	2.3907
===== End of Observation Set =====					
2001	-2708941.0950				
	-4142050.6320				
	4010040.8370				
2002	-2709227.7640	0.0030	-0.0046	0.0020	-2.2625
	-4142743.8510	0.0040	-0.0036	0.0031	-1.1706
	4009149.2480	0.0040	0.0072	0.0032	2.2786
===== End of Observation Set =====					
2001	-2708946.1080				
	-4142048.2180				
	4010039.9500				
2002	-2709232.7870	0.0040	0.0054	0.0033	1.6090
	-4142741.4410	0.0040	0.0004	0.0031	0.1285
	4009148.3720	0.0040	-0.0038	0.0032	-1.1993
===== End of Observation Set =====					
2014	-2713050.5170				
	-4145286.8310				
	4003867.5850				
2002	-2709251.5120	0.0180	-0.0035	0.0149	-0.2328
	-4142732.8130	0.0160	-0.0015	0.0090	-0.1659
	4009164.3830	0.0200	0.0047	0.0141	0.3373
===== End of Observation Set =====					
2013	-2709663.6000				
	-4137421.4500				
	4014263.6620				
2014	-2713031.0290	0.0150	-0.0018	0.0105	-0.1739
	-4145312.4700	0.0460	0.0055	0.0419	0.1303
	4003852.9890	0.0330	0.0010	0.0293	0.0344

-----  
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696] Page 10  
-----

Figure F-12d. GEOLAB Adjustment Output (Constrained)

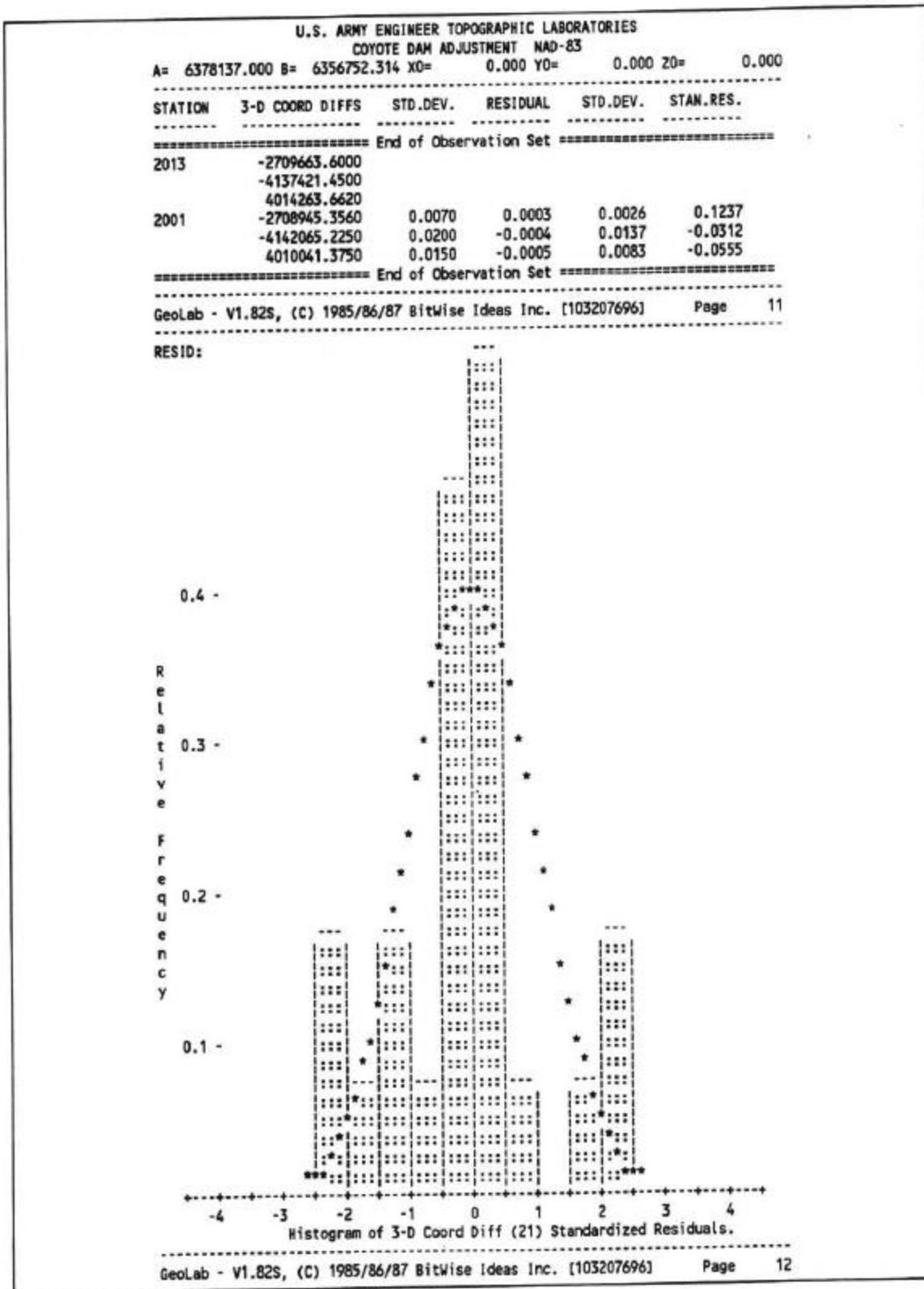


Figure F-12e. GEOLAB Adjustment Output (Constrained)

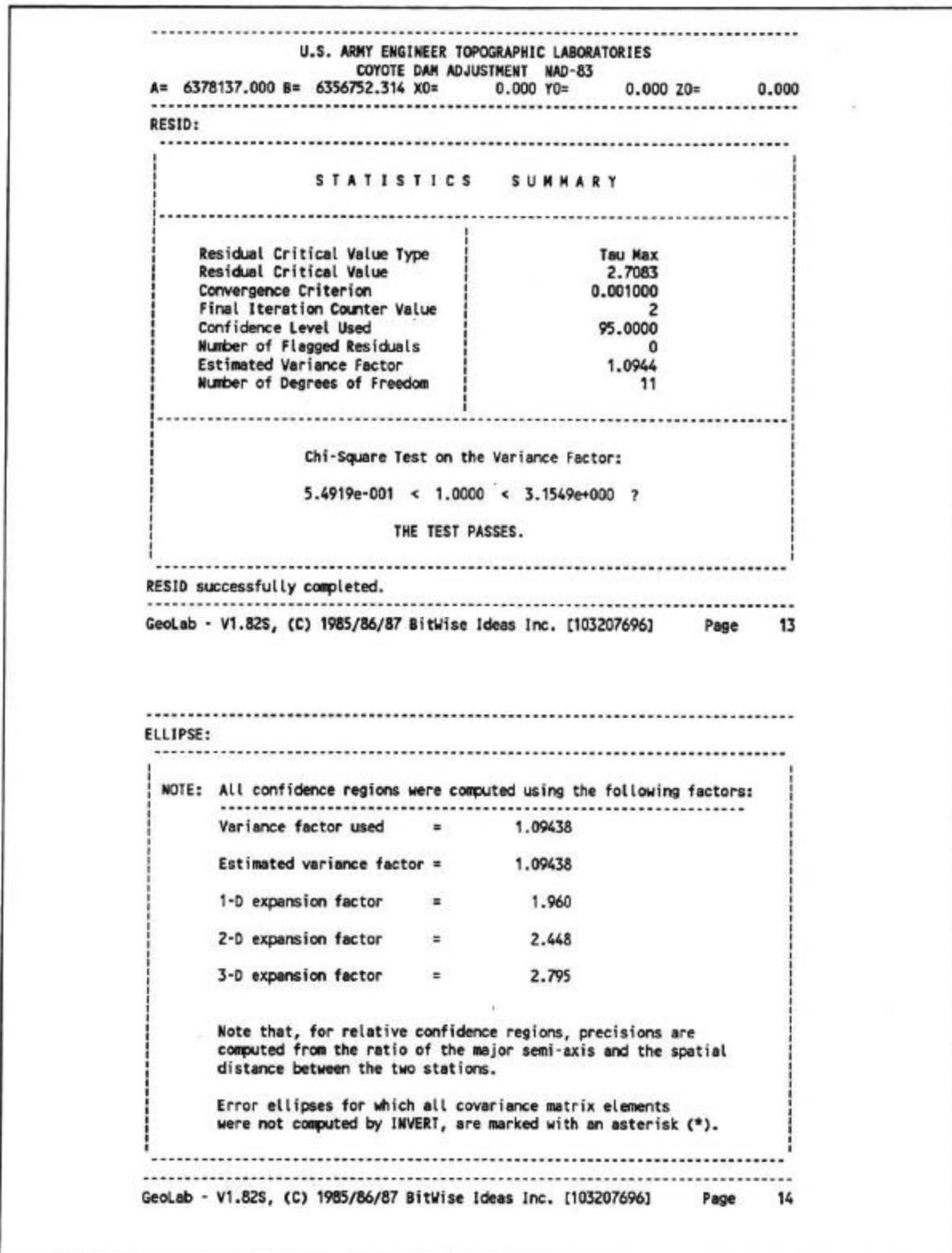


Figure F-12f. GEOLAB Adjustment Output (Constrained)

```

-----
                                U.S. ARMY ENGINEER TOPOGRAPHIC LABORATORIES
                                COYOTE DAM ADJUSTMENT NAD-83
A= 6378137.000 B= 6356752.314 X0= 0.000 Y0= 0.000 Z0= 0.000
-----
ELLIPSE:                AUXILIARY PARAMETER CONFIDENCE INTERVALS ( 95.000 %):
-----
IDENT.  TYPE  CLASS  ADJ VALUE  1.96 SIGMA
-----
WGSXX   300   SCAL   -0.0016   1.1261
          ROTX   0 0  0.03  0 0  0.82
          ROTY   0 0 -0.06  0 0  1.27
          ROTZ   0 0 -0.04  0 0  1.37
-----
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]   Page 15
-----

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```

ELLIPSE:                2-D AND 1-D STATION CONFIDENCE REGIONS ( 95.000 %):
-----
IDENT.  MAJOR SEMI-AXIS  MINOR SEMI-AXIS  AZ(MAJ)  VERTICAL
-----
2001    0.0066           0.0048          107.22   0.0133
2002    0.0062           0.0044          125.62   0.0127
-----
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]   Page 16
-----

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```

ELLIPSE:                2-D AND 1-D RELATIVE STATION CONFIDENCE REGIONS ( 95.000 %):
-----
FROM    TO    MAJ.SEMI  MIN.SEMI  AZ(MAJ)  VERTICAL  SPATIAL DIST.  PRECISION
-----
2001    2002    0.0045   0.0036   108.07   0.0082   1165.1856      3.846 PPM
-----
GeoLab - V1.82S, (C) 1985/86/87 BitWise Ideas Inc. [103207696]   Page 17
-----

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```

ELLIPSE:                3-D STATION CONFIDENCE REGIONS ( 95.000 %):
-----
IDENT.  MAJOR SEMI-AXIS  MEDIUM SEMI-AXIS  MINOR SEMI-AXIS
-----
2001    0.0191           0.0070           0.0056
          A=106.6 V= 81.9   A=270.0 V= 7.8   A= 0.3 V= 2.3
2002    0.0182           0.0070           0.0051
          A= 90.0 V= 87.6   A=306.2 V= 1.9   A=216.2 V= 1.4
-----
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```

ELLIPSE:                3-D RELATIVE STATION CONFIDENCE REGIONS ( 95.000 %):
-----
FROM    TO    MAJOR-SEMI  MED.-SEMI  MINOR-SEMI  SPATIAL DIST.  PRECISION
-----
2001    2002    0.0117     0.0050     0.0042     1165.1856     10.027 PPM
          A= 0 V=90 A= 90 V= 0 A= 0 V= 0
ELLIPSE successfully completed.
-----
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Figure F-12g. GEOLAB Adjustment Output (Constrained)